Free Convection in a Darcy Thermally Stratified Porous Medium That Embeds a Vertical Wall of Constant Heat Flux and Concentration

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Abstract—This paper presents the heat and mass driven natural convection succession in a Darcy thermally stratified porous medium that embeds a vertical semi-infinite impermeable wall of constant heat flux and concentration. The scale analysis of the system determines the two possible maps of the heat and mass driven natural convection sequence along the wall as a function of the process parameters. These results are verified using the finite differences method applied to the conservation equations.

Keywords—Finite difference method, natural convection, porous medium, scale analysis, thermal stratification.

I. INTRODUCTION

The natural convection triggered by a vertical semi-infinite porous wall embedded in a porous medium was intensively analyzed by scientific researchers in the last decades [1]-[22]. Due to the wide variety of its practical applications, different cases were considered, analyzed, and developed: the wall of constant [1]-[3] or variable [4],[5] temperature, constant [1] or variable [6] heat flux, constant [7]-[13] or variable concentration, constant concentration and variable heat flux [14],[15], variable heat and mass flux [16]; the non-Darcy porous medium [6],[17]; the dispersion effects analysis [7],[18]; the non-Newtonian fluid saturated porous medium [1],[16],[18]; the consideration of the Soret and the Dufour effects [15],[17]; the thermally [2]-[4],[8],[19]-[21] or the double stratified environment [22], etc. These analyses establish the heat and/or the mass transfer at the wall as well as the temperature, the concentration and the velocity fields in the boundary layer by using various methods: the scale analysis [1],[7],[10],[13], the similarity [3],[7],[10],[12]-[16],[18],[19] or the non-similarity [4],[5] techniques, the finite differences method [4],[8],[9],[11],[13],[15], the spline collocation method [2],[16], the fourth-order Runge-Kutta integration method [5],[10],[14],[17],[19], etc. In this scientific environment, this paper establishes the succession of the heat and mass driven natural convection regimes that attain the equilibrium state along a vertical impermeable wall of constant heat flux and concentration, a wall that is embedded in a Darcy thermally stratified porous medium. While the scale analysis of the system reveals the order of magnitude of the boundary layers variables as well as the two possible natural convection regime sequences, the finite differences method is used to verify these results.

II. MATHEMATICAL FORMULATION

A vertical semi-infinite impermeable wall embedded in a Darcy fluid- saturated porous medium is presented by Fig. 1 (a). The wall releases a uniform constant heat flux \( q_w \) and the concentration of a certain constituent is constant at the wall \( (C_{w}) \). The origin of the coordinate system is fixed at the leading edge of the wall, \( x \) and \( y \) being the vertical and horizontal coordinates, respectively. At a distance sufficiently far from the wall, \( y_e \), the environment temperature varies linearly with the vertical coordinate: \( T_{x,y} = T_{x,y} + s_{T}x \), where \( s_T \) is the dimensional thermal stratification coefficient: 
\[
s_T = \frac{dT_{x,y}}{dx}.
\]

The height of the computational domain is \( h \).

All the properties are constant except for the fluid density, \( \rho \), that obeys the Boussinesq approximation:
\[
\rho = \rho_0 \left[ 1 - \beta_r (T - T_n) - \beta_c (C - C_n) \right],
\]
where \( \rho_0 \) is the reference density, while \( \beta_r \) and \( \beta_c \) are the thermal and concentration expansion coefficient, respectively.

The governing equations of the system, after the elimination of the pressure terms, are:
\[
\frac{\partial \bar{v}}{\partial x} + \frac{\partial \bar{u}}{\partial y} = 0; \tag{1}
\]
\[
\frac{\partial \bar{v}}{\partial y} + \frac{\partial \bar{u}}{\partial x} = \rho \beta_r \frac{\partial T}{\partial y} + \rho \beta_c \frac{\partial C}{\partial y}; \tag{2}
\]
\[
\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} = \alpha \left( \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right); \tag{3}
\]
\[
\frac{\partial C}{\partial t} + u \frac{\partial C}{\partial x} + v \frac{\partial C}{\partial y} = D \left( \frac{\partial^2 C}{\partial x^2} + \frac{\partial^2 C}{\partial y^2} \right). \tag{4}
\]

In (3) and (4), the following notations were used: \( u \) and \( v \) are the dimensional velocity components on the \( x \) and \( y \) directions, \( T \)—the dimensional temperature, \( C \)—the dimensional concentration, \( t \)—the dimensional time, \( g \)—the gravitational acceleration, \( K \)—the porous medium permeability, \( \mu \)—the dynamic viscosity, \( \alpha \)—the thermal diffusivity, \( D \)—the diffusion coefficient of the species.
The governing equations in non-dimensional form:

\[
\frac{\partial V}{\partial X} + \frac{\partial U}{\partial Y} = 0;
\]

\[
\frac{\partial V}{\partial Y} - \frac{\partial U}{\partial X} = Ra \frac{\partial \theta}{\partial Y} + N \frac{\partial \phi}{\partial Y};
\]

\[
\frac{\partial \theta}{\partial \tau} + V \frac{\partial \theta}{\partial X} + VS_T U \frac{\partial \theta}{\partial Y} + \frac{\partial^2 \theta}{\partial X^2} + \frac{\partial^2 \theta}{\partial Y^2};
\]

\[
\frac{\partial \phi}{\partial \tau} + V \frac{\partial \phi}{\partial X} + U \frac{\partial \phi}{\partial Y} = \frac{1}{Le} \left( \frac{\partial^2 \phi}{\partial X^2} + \frac{\partial^2 \phi}{\partial Y^2} \right),
\]

and the dimensionless boundary conditions:

\[
U = 0 , \frac{\partial \theta}{\partial Y} = -1 , \phi = 1 \text{ at } Y = 0 ;
\]

\[
V = 0 , \theta = \phi = 0 \text{ as } Y \to \infty ;
\]

\[
V = 0 , \theta = \phi = 0 \text{ at } X = 0 ;
\]

\[
\frac{\partial^2 U}{\partial X^2} + \frac{\partial^2 V}{\partial X^2} = \frac{\partial^2 \theta}{\partial X^2} = \frac{\partial^2 \phi}{\partial Y^2} = 0 \text{ at } X = H ,
\]

are determined by replacing (6) in (1)-(5). The following parameters occur in (7)-(11): \( Ra = \left[ K \beta g q_s / k L^2 / \alpha v \right] \), the Darcy–modified Rayleigh number based on heat flux, \( N = \left[ \beta \left( C_w - C_{\infty} \right) / \beta [ q_s L / k ] \right] \), the buoyancy ratio, \( S_T = \left[ S_T / ( q_s L / k ) \right] \), the dimensionless thermal stratification parameter, and \( Le = ( \alpha / D ) \), the Lewis number.

The scale analysis [24] of the dimensionless governing equations, (7)-(10), is realized in the following section, Section III. Section IV presents the numerical model used to solve the dimensionless governing equations and to verify the results established in Section III of this paper.

### III. SCALE ANALYSIS

The initial moments, when the equilibrium state is not reached, are analyzed by Subsection A, while Subsections B and C present the scale analysis of the equilibrium state: B–the mass driven convection regime (MDC), C–the heat driven convection regime (HDC).

#### A. Scale Analysis of the Transient Stage

In the first moments, before the system reaches the equilibrium state, in the energy conservation equation, (9), the equilibrium between the inertia and the diffusion of heat in the \( Y \) direction is attained:

\[
\frac{\partial \theta}{\partial \tau} \sim \frac{x^2 \phi}{\partial X^2}.
\]
As the temperature difference across the thermal boundary layer is $\Delta \theta$ and $Y \sim \delta_Y$, the temperature boundary layer thickness in the transient regime, $\delta_Y$, becomes:

$$\delta_Y \sim \tau^{1/2}.$$  \hspace{1cm} (13)

Similarly, in the species conservation equation, (10), the equilibrium between the inertia and the diffusion in the $Y$ direction, $\partial \phi / \partial t \sim 1 / \cal{Le} \cdot \partial^2 \phi / \partial Y^2$, reveals the thickness of the concentration boundary layer, $\delta_c$:

$$\delta_c \sim \tau^{1/2} / \cal{Le}^{1/2}.$$  \hspace{1cm} (14)

Assuming that the temperature and the concentration boundary layers thickness scale $\delta_Y << X$ and $\delta_c << X$, we neglect the $\partial U / \partial X$ term in (8):

$$\frac{\partial V}{\partial Y} = Ra \cdot \left( \frac{\partial \theta}{\partial Y} + Ra \cdot N \cdot \frac{\partial \phi}{\partial Y} \right).$$  \hspace{1cm} (15)

Integrating (15) from $Y = 0$ to infinity, we obtain:

$$V \sim Ra \cdot \Delta \theta + Ra \cdot N \cdot \Delta \phi.$$  \hspace{1cm} (16)

Taking into account that the temperature difference across the temperature boundary layer is $\Delta T \sim T_s \delta_Y \sim T_s \alpha^{1/2} \tau^{1/2}$ or $\Delta \theta \sim \tau^{1/2}$, the first term on the right hand side of (16) ($V_T$–the vertical velocity due to the buoyancy force that is determined by the volumetric thermal expansion) can be written as:

$$V_T \sim Ra \cdot (\Delta \theta) \sim Ra \cdot \tau^{1/2}.$$  \hspace{1cm} (17)

The concentration difference across the concentration boundary layer is $\Delta C \sim (C_w - C_v)$ or $\Delta \phi \sim 1$ and, consequently, the second term on the right hand side of (16) ($V_c$–the vertical velocity due to the buoyancy force that is determined by the volumetric concentration expansion) becomes:

$$V_c \sim Ra \cdot N \cdot (\Delta \phi) \sim Ra \cdot N.$$  \hspace{1cm} (18)

Using (16)–(18), the order of magnitude of the vertical velocity field is given by:

$$V \sim Ra \cdot \tau^{1/2} + Ra \cdot N.$$  \hspace{1cm} (19)

The analysis of (19) shows that the $V_T$ increases in time, while $V_c$ is constant. Consequently, a mass driven convection (MDC) regime dominates initially at each $X$-constant level, but, if the equilibrium time, $\tau_{eb}$, is bigger than the transition time, $\tau_{trz}$:

$$\tau_{eb} < \tau_{trz} = N^2.$$  \hspace{1cm} (20)

A heat driven convection (HDC) regime will be installed and it will reach the equilibrium state at that abscissa. It is the aim of this paper to establish the maps of the equilibrium mass and heat driven natural convection regimes that appear in the boundary layer near the vertical wall. In order to draw these maps, the scale analysis of the mass and heat driven convection regimes will be analyzed in the next two subsections.

B. Scale Analysis of the Mass Driven Convection (MDC) Regime

In the mass driven convection regime, the equilibrium is reached when the mass flux diffused in the $Y$ direction equals the mass flux convected in the $X$ direction:

$$V \cdot \frac{\Delta \phi}{\partial Y} \sim \frac{1}{\cal{Le}} \frac{\Delta \phi}{\partial Y}.$$  \hspace{1cm} (21)

The order of magnitude of the time when the equilibrium is attained is established by replacing the vertical velocity with the component dominant in the MDC regime, (18), and $\delta_c$ from (14):

$$\tau_c \sim \frac{X}{(Ra \cdot N)}. \hspace{1cm} (22)$$

At this moment, according to (14), the concentration boundary layer thickness is:

$$\delta_{eb,c} \sim (X / (Ra \cdot N))^{1/2}.$$  \hspace{1cm} (23)

The equilibrium time, $\tau_c$, is bigger than the transition time, $\tau_{trz}$, only if

$$X_{trz} = Ra \cdot N^4 < X.$$  \hspace{1cm} (24)

Further, this study is completed by analyzing the temperature field in the mass driven convection regime.

C. Scale Analysis of the Temperature Field in the Mass Driven Convection Regime

For a complete understanding of the temperature field in the mass driven convection regime, the relative magnitude of the two vertical convective terms, $V \cdot S_T$ and $V \cdot \partial \theta / \partial X$, in the energy conservation equation, (9), must be analyzed. The $V \cdot S_T$ term is dominant if $S_T \tau > \tau^{1/2} / X$ or

$$\tau < \tau_s = S_T \tau^2 X^2.$$  \hspace{1cm} (25)

As (25) tells us, at the beginning, when $\tau < \tau_s$, the $V \cdot S_T$ term is dominant but, in time, this situation remains unchanged or not depending on the relative magnitude of $\tau_s$. 

Further, the equilibrium time will be established for the two situations that could be encountered:

a) If (9) is characterized by the dominance of the $V \cdot \partial \theta / \partial X$ term, then, its scale analysis reveals that:

$$V \frac{\partial \theta}{\partial X} \sim \frac{\partial^2 \theta}{\partial Y^2}.$$  \hfill (26)

The time when the temperature field reaches the equilibrium state is found by replacing (18) and (13) in (26):

$$\left(\tau_{ech, C}\right)_C \sim \frac{X}{Ra \cdot N}.$$  \hfill (27)

As we can notice, for this situation, the temperature and the concentration fields attain the equilibrium state in the same moment as $\tau_C$, (22), and $\left(\tau_{ech, C}\right)_C$, (27), have the same form.

Using (13), at the equilibrium state, the temperature boundary layer thickness is:

$$\left(\delta_{ech, C}\right)_C \sim \left[\frac{X}{Ra \cdot N}\right]^{1/2}.$$  \hfill (28)

b) If the $V \cdot S_T$ term is the dominant vertical convection term in (9), then the scale analysis reveals that:

$$V \cdot S_T \sim \frac{\partial^2 \theta}{\partial Y^2}.$$  \hfill (29)

Using (13) and (18), we conclude that the moment when the equilibrium is attained has the order of magnitude

$$\left(\tau_{ech, ST}\right)_C \sim \left[1/(Ra \cdot N \cdot S_T)\right]^2$$

and that the magnitude of the equilibrium temperature boundary layer thickness is:

$$\left(\delta_{ech, ST}\right)_C \sim 1/(Ra \cdot N \cdot S_T).$$  \hfill (30)

Further, the equilibrium time $\left(\tau_{ech, ST}\right)_C$ will be compared to $\tau_{yz}$ and $\tau_s$:

b1) The equilibrium time $\left(\tau_{ech, ST}\right)_C$ is smaller than the transition time, $\tau_{yz}$, on the domain defined by (31):

$$Ra \cdot N^2 \cdot S_T > 1 .$$  \hfill (31)

b2) The possibility to have $\left(\tau_{ech, ST}\right)_C < \tau_s$ is restricted to the domain defined below:

$$X > \frac{1}{Ra \cdot N \cdot S_T^2}.$$  \hfill (32)

Two distinct situations appear:

1. If (31) is valid, then the mass→heat driven convection transformation is taking place for abscissa greater than $X_{ech, C}$ ((24) and Fig. 2 (a)).

2. If (31) is not valid, $Ra \cdot N^2 \cdot S_T < 1$ and the mass→heat driven convection transition is taking place after the $V \cdot \partial \theta / \partial X$ term becomes dominant.

In order to establish the abscissa where the HDCT—HDCSt transition is taking place, the scale analysis of the HDC regime is presented in the next section.

C. Scale Analysis of the Heat Driven Convection Regime

Two heat driven convection regime types: HDCSt regime (the $V \cdot \partial \theta / \partial X$ term is dominant and (25) is valid, Subsection C 1.) and HDC regime (the $V \cdot \partial \theta / \partial X$ term is dominant, Subsection C 2.) are encountered and they will be treated separately.

1. HDCSt Regime

The equilibrium state in the HDCSt regime is reached in the moment when the diffusion of heat away from the wall, in the $Y$ direction, equals the convection of heat expressed by the $V \cdot S_T$ term.
\[ V \cdot S_T \sim \frac{\partial^2 \theta}{\partial Y^2}. \] (33)

Replacing (13) and (17) in (33), we obtain the equilibrium time:

\[ \left( r_{ech,ST} \right)_T \sim 1/(S_T \cdot Ra). \] (34)

At this moment, the temperature boundary layer thickness is

\[ \left( \delta_{ech,ST} \right)_T \sim 1/\sqrt{S_T \cdot Ra}. \] (35)

This state of equilibrium is attained before the transition HDCSt \( \rightarrow \) HDC if \( \left( r_{ech,ST} \right)_T < r_c \) or

\[ X > 1/\sqrt{Ra \cdot S_T^2}. \] (36)

This is the condition that separates the HDC and HDCSt regimes in Fig. 2 (b).

For the \( Ra \cdot N^2 \cdot S_T > 1 \) case (Fig. 2 (a)),

\[ 1/\sqrt{Ra \cdot S_T^2} < Ra \cdot N^2 \]

and we can verify once again that a HDCSt regime is installed beyond \( X_{ech} \) abscissa.

2. HDC Regime

In the region where the \( V \cdot \partial \theta / \partial X \) term is dominant, the equilibrium state is characterized by: \( V \cdot \Delta \theta / X \sim \Delta \theta / \delta^2 \).

The equilibrium time is:

\[ \left( r_{ech} \right)_T \sim (X / Ra)^{2/3}. \] (37)

and the thermal boundary layer thickness becomes:

\[ \left( \delta_{ech} \right)_T \sim (X / Ra)^{2/3}. \] (38)

D. Scale Analysis of the Concentration Field in the Heat Driven Convection Regime

The scale analysis of (10) reveals that

\[ V \cdot \partial \phi / \partial X \sim 1/Le \cdot \partial^2 \phi / \partial Y^2. \]

Using (14) and (17), the time when the concentration field attains the equilibrium state is:

\[ \left( r_{ech} \right)_T \sim (X / Ra)^{5/3}. \] (39)

The concentration boundary layer thickness is:

\[ \left( \delta_{ech,c} \right)_T \sim 1/Le^{1/2} (X / Ra)^{1/3}. \] (40)

Imposing the condition for the thermal boundary layer approximation validity: \( \left( \delta_{ech,ST} \right)_T \ll 1/(RaNS_T^2) \) if \( Ra \cdot N^2 \cdot S_T > 1 \) or \( \left( \delta_{ech,ST} \right)_T \ll 1/(RaNS_T^2) \) if \( Ra \cdot N^2 \cdot S_T < 1 \), we obtain the same requirement: \( S_T \ll 1.0 \). As \( \left( \delta_{ech,c} \right)_T \ll \left( \delta_{ech,c} \right)_C \) if \( X > RaN^3 \), the validity of the concentration boundary layer approximation, \( \left( \delta_{ech,c} \right)_C \ll X \), imposes the condition: \( X \gg 1/(LeRaN) \) and it defines "a diffusive region" [23] that occurs for small values of \( X \).

IV. NUMERICAL MODELING

Using a stream function formulation for the velocity field: \( U = -\partial \psi / \partial X \), \( V = \partial \psi / \partial Y \), the new form of the dimensionless governing equations is given by (40)–(42):

\[ \partial^2 \psi / \partial y^2 + \partial^2 \psi / \partial x^2 = Ra \left( \partial \theta / \partial Y + N \partial \phi / \partial Y \right); \] (40)

\[ \partial \theta / \partial t + \partial \psi / \partial y \partial \theta / \partial y + S_T \partial \psi / \partial y \partial \theta / \partial y = \partial^2 \theta / \partial x^2 + \partial^2 \theta / \partial y^2; \] (41)

\[ \partial \phi / \partial t + \partial \psi / \partial y \partial \phi / \partial y + \partial \psi / \partial y \partial \phi / \partial y = \frac{1}{Le} \partial^2 \phi / \partial x^2 + \partial^2 \phi / \partial y^2. \] (42)

The following boundary conditions apply to (40)–(42):

\[ \psi = 0, \partial \theta / \partial y = -1, \phi = 1 \text{ at } Y = 0; \] (43a)

\[ \partial \psi / \partial y = 0, \theta = \phi = 0 \text{ as } Y = L; \] (43b)

\[ \psi = 0, \theta = \phi = 0 \text{ at } X = 0; \] (43c)

\[ \partial^2 \psi / \partial x^2 = \partial^2 \phi / \partial x^2 = \partial^2 \phi / \partial y^2 = 0 \text{ at } X = H; \] (43d)

The governing equations, (40)-(42), subjected to the boundary conditions, (43), were solved numerically using the finite difference method, the higher order hybrid scheme – the “QUICK scheme” [25], [26]. Second-order finite-difference representation was used for all the terms of (40); third-order one-sided finite-difference representation was used for the convection terms at the boundary points in (41) and (42); the left boundary of (41) received a first-order finite-difference representation of (43a) using an external point. The influence of the number of the grid points, the upper limit of the computational domain, the time step and the variables relative error on the results (the Nusselt number, the Sherwood number, the values of the temperature and the concentration fields) was analyzed. The program was also tested with good results using the boundary conditions and the data already published in the literature [27]-[29].

V. RESULTS AND DISCUSSIONS

The MDC \( \rightarrow \) HDC \( \rightarrow \) HDCSt regime sequence that is encountered for the \( Ra \cdot N^2 \cdot S_T < 1 \) case was verified using the \( Ra = 300, N = 0.2, Le = 1 \) and \( S_T = 0.02 \) case. A domain with \( H = 25 \) and \( Y_S = 0.7 \) was discretized using \( 1251 \times 71 \) points uniformly distributed along the \( X \) and \( Y \) direction,
respectively, a situation that proved to assure a high accuracy of the results: the Nusselt and the Sherwood numbers have a precision higher than 2%, while the relative error for the temperature, concentration and stream function fields in each point is less than 10^-6. The results of Section III show that MDC_T—HDC_T transition takes place at the \(Ra \cdot N^2 = 2.4\) and that the HDC_T—HDC_st transition occurs at \(1/\sqrt{RaS_T^2} = 20.4\) abscissa. Fig. 3 presents the dimensionless temperature (Fig. 3 (a)), concentration (Fig. 3 (b)), and stream function (Fig. 3 (c)) and \((\partial \theta / \partial x) / S_T\) (Fig. 3 (d)) fields for the considered case. Fig. 3 (a) shows values of the temperature field greater than 0.2 for \(X \geq 1.84\) and, in this way, it reveals the MDC_T—HDC_T transition point. Fig. 3 (d) shows values of \((\partial \theta / \partial x) / S_T\) smaller than 1.0 for \(X \geq 3.6\); it verifies the HDC_T—HDC_st transition. The difference between the analytical values (20.4) and the numerical value (3.6) of this transition abscissa is due to the approximations induced by the scale analysis method.

In the MDC_T region, Figs. 4 (a)-(c) present the temperature, concentration and vertical velocity fields for three abscissas: 0.67, 0.83; 1.0. Making use of (28), (23) and (18), Figs. 4 (d)-(f) present the scaled temperature, concentration and vertical velocity fields as a function of the scaled ordinate for the same abscissa. The collapse of these graphs on the same curve, proves the validity of the scaling dimensions determined previously.

Figs. 5 (a)-(c) present the temperature, concentration and velocity fields for three abscissas: 2.67, 3.0 and 4.0 belonging to the HDC_T region. Figs. 5 (d)-(f) present the scaled temperature, concentration and vertical velocity fields as a function of the scaled ordinate for the same abscissa mentioned above and making use of the results given by (38), (39), (37) and (17).

Figs. 6 (a)-(c) present the temperature, concentration and velocity fields for the following abscissas: 21.0, 22.0 and 24.0 of the HDC_st region. For the same abscissas, using (35), (39), (34) and (17), Figs. 6 (d)-(f) present the scaled temperature, concentration and velocity fields as a function of the scaled ordinate giving a verification of the natural convection regime and the scaled defined for this region.
The $Ra \cdot N^2 \cdot S_r > 1$ case (Fig. 2 (a)), the MDC$_T$—MDC$_{St}$—HDC$_{Sf}$ natural convection regimes sequence will be verified considering the $Ra = 600$, $N = 0.2$, $Le = 1$ and $S_r = 0.05$ system. A domain with $H = 6$ and $Y_m = 0.4$ was discretized using $606 \times 46$ points uniformly distributed, a situation that assures the same accuracy as for the previous case. The results of Section III indicate that the MDC$_T$—MDC$_{St}$ transition takes place at the $1/(RaNS_r^2) = 3.34$ abscissa and that the MDC$_{St}$—HDC$_{St}$ transition occurs at $Ra \cdot N^2 = 4.8$ abscissa. The numerical modeling results presented by Fig. 7 show that the $(\partial \theta / \partial X) / S_r$ values become smaller than 1.0 (i.e., the MDC$_{St}$ regime occurs) for $X \geq 1.02$, while the temperature field has values greater than 0.2 (i.e., the MDC$_{St}$—HDC$_{St}$ transition occurs) for $X \geq 4.4$.

The MDCT region and its scaling results were verified using the temperature, concentration and vertical velocity plots at the following abscissas: 0.5, 0.67 and 0.83 (Figs. 8 (a)-(c)), while Figs. 8 (d)-(f) present the scaled temperature, concentration and vertical velocity field variations as a function of scaled ordinate, for three abscissas: 2.67, 3.0 and 4.0, $Ra = 300$, $N = 0.2$, $Le = 1$ and $S_r = 0.02$.
concentration and velocity fields as a function of the scaled ordinate for the same abscissas. The collapse of these graphs on the same curve, prove the validity of the scaling dimensions determined previously.

Figs. 9 (a)-(c) present the temperature, concentration and vertical velocity fields for three abscissas: 3.5, 3.75 and 4.0 in the MDCSt section. Figs. 9 (d)-(f) present the scaled temperature, concentration and velocity fields as a function of the scaled ordinate making use of (30), (23) and (18).

The HDCSt region results were proved by plotting the temperature, concentration and velocity fields for the following abscissas: 5.0, 5.4 and 5.8 (Figs. 10 (a)-(c)). For the same abscissas, using the results given by (35), (39), (34) and (17), Figs. 10 (d)-(f) present the scaled temperature, concentration and vertical velocity fields as a function of the scaled ordinate giving a verification of the natural convection regime and the results obtained for this region.

The results presented by Figs. 3-10 prove the succession of the heat/mass transfer regimes for the two possible cases revealed by the scale analysis of the system.
VI. CONCLUSION

The natural convection process that is taking place in a fluid-saturated Darcy thermally stratified porous medium that embeds a vertical impermeable wall of constant heat flux and concentration is an array of mass and heat driven convection regimes that attain the equilibrium state along the wall.

If $Ra \cdot N^2 \cdot S_T > 1$, after the first region, where a mass driven convection regime (MDC$_T$) is present, an intermediate MDC$_{St}$ regime is followed by an HDC$_S$ regime.

If $Ra \cdot N^2 \cdot S_T < 1$, then, at equilibrium, after the first MDC$_T$ region, we encounter a HDC$_T$ region followed by an HDC$_{St}$ region.

This paper brings a new understanding of the important natural convection process triggered in a fluid-saturated...
thermos stratified porous medium by a vertical impermeable wall of constant heat flux and concentration. This work triggers similar analysis regarding a doubly stratified Darcy porous medium, a vertical wall of constant temperature and mass flux, etc.

REFERENCES


