Modeling and Investigation of Elongation in Free Explosive Forming of Aluminum Alloy Plate

R. Alipour, F. Najarian

Abstract—Because of high ductility, aluminum alloys, have been widely used as an important base of metal forming industries. But the main weak point of these alloys is their low strength so in forming them with conventional methods like deep drawing, hydro forming, etc have been always faced with problems like fracture during of forming process. Because of this, recently using of explosive forming method for forming of these plates has been recommended. In this paper free explosive forming of A2024 aluminum alloy is numerically simulated and during it, explosion wave propagation process is studied. Consequences of this simulation can be effective in prediction of quality of production. These consequences are compared with an experimental test and show the superiority of this method to similar methods like hydro forming and deep drawing.

Keywords—free explosive forming, CEL, Johnson – cook

I. INTRODUCTION

Aluminum weight is about 1/3 of steel in the same volume [2] so now a day’s aluminum alloys has found wide application, as a substitute of steel, in industries like aerospace, automotive and military [1]. The most important weak point of aluminum, Compared with steel, is it’s elasticity that causes fracturing during the forming. This problem is more seen during the forming by using usual method like hydro forming and deep drawing.

So recently, free explosive forming method for forming aluminum alloys has been in the center of attention [3, 4]. An explosive forming system schematic for aluminum parts production is shown Figure 1. As it is seen in this situation the blank is between to blank holder and above it there is a water tank.

Spherical explosive charge is above the blank in the water and in the distance called stand off. Explosive geometry and mass are chosen according to data in the in the references [5]. All measures for modeling of this process have been set according to experimental tests [6].

II. PROCESS MODELING

A. Modeling Method

According what is mentioned in references of this paper [7] Couple Eulerian Lagrangian (CEL) base on FEM, is the best possible way to model this process. So the mentioned model is used to this process. All the modeling and analyses steps are done by LS_DYNA_971 software.

B. Explosive Modeling

The explosive used in the simulation of PETN which its properties are in table1 [6]. $P_{cj}$ and $d_{cj}$ are the highest pressure and highest velocity produced by explosion of explosive base on Chapman-Jouguet respectively. Explosive geometry is considered spherical. To model the explosive in LS_DYNA_971 software the model of High_Explosive_Burn is used.

C. Water Modeling

The model of MAT_NULL is used for water modeling in LS_DYNA_971 software that doesn’t bear shear stress and seems convenient for fluid materials modeling [8]. In fact water as an energy transfer media with higher density, compared with air, plays the role as transmission material for transferring of explosion wave from charge to blank. Even though, there is around a tank around the water, but in this model instead of tank a rigid wall has been stretched around the elements of water.

TABLE I

<table>
<thead>
<tr>
<th>Charge Type</th>
<th>$\rho$ (kg/m$^3$)</th>
<th>$d_{cj}$ (km/s)</th>
<th>$P_{cj}$ (Gpa)</th>
</tr>
</thead>
<tbody>
<tr>
<td>PETN</td>
<td>1.763</td>
<td>8.274</td>
<td>31.5</td>
</tr>
</tbody>
</table>

Fig.1 An explosive forming system schematic

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D. Modeling of Aluminum Blank

Aluminum disk is considered of A2024 for description of range of effective stress rate on blank the Johnson – Cook equation has a lot of applications in the modeling of this problem by considering work hardening, strain rate, temperature variations, etc [9]. Formula 1 shows Johnson – Cook equation.

\[
\sigma = (A + B\varepsilon^\dot{\varepsilon})[(1 + C\ln \varepsilon^\dot{\varepsilon})(1 - T^n)]
\]

(1)

Where \(\varepsilon\) is equivalent plastic strain, \(\dot{\varepsilon}\) is plastic strain rate for \(\varepsilon_0 = 1\), that \(T\) is absolute temperature for \(T^* = \frac{T - T_{melt}}{T_{melt} - T_{room}}\) and \(A, B, C, n\) and \(m\) are constant. Constants in this equations is obtained from simple mechanical tests such as isothermal tension and torsion tests, that is given in Table 2 for the materials used in this study.

**TABLE II**

<table>
<thead>
<tr>
<th>MATERIAL</th>
<th>A (MPa)</th>
<th>B (MPa)</th>
<th>C (MPa)</th>
<th>M</th>
<th>n</th>
<th>T_{melt} (K)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A2024</td>
<td>265</td>
<td>465</td>
<td>0.015</td>
<td>0.34</td>
<td>0.5</td>
<td>775</td>
</tr>
</tbody>
</table>

E. Equation of States

In addition to conservation essential equations including, mass conservation, linear and angular momentum conservation and energy conservation, in problems that are followed by intensive pressure, stress or volume variations there is a need to equation between thermodynamics properties (pressure, density and temperature). One of most applied equation of state for explosive is JWL\(^1\) equation and Mie-Gruneisen for metal and water [10, 11].

Equation of JWL is in the form of equation 2.

\[
P = C_1(1 - \frac{\varepsilon_0}{r_1})e^{-r_1} + C_2(1 - \frac{\varepsilon_0}{r_2})e^{-r_2} + \frac{\alpha V}{V_0}
\]

(2)

Where \(C_1, C_2, r_1, r_2\) and \(\alpha\) are the constants of JWL equation. \(V\) is the ratio of the volume of the product gases to initial volume of undetonated explosive. The constant is given in Table 3 for the PETN [6] used in this investigation.

**TABLE III**

<table>
<thead>
<tr>
<th>MATERIAL</th>
<th>A (GPa)</th>
<th>B (GPa)</th>
<th>C (GPa)</th>
<th>R_1</th>
<th>R_2</th>
<th>(\alpha)</th>
</tr>
</thead>
<tbody>
<tr>
<td>PETN</td>
<td>1032.158</td>
<td>90.57014</td>
<td>3.72735</td>
<td>6</td>
<td>2.6</td>
<td>0.57</td>
</tr>
</tbody>
</table>

Equation of Mie-Gruneisen is in the form of equation 3.

\[
P = \rho_0 S C_0 \eta \left[ \frac{1 - \Gamma_0 \eta}{2} \right] + \Gamma_0 \rho_0 E
\]

(3)

Where \(\rho_0\) is initial density. \(E\) is internal energy. \(\Gamma_0\) is Gruneisen parameter. \(\eta = 1 - \rho / \rho_0\), \(C_0\) and \(S\) are material constants. For the related materials, the values of those constants are given in table 4 [3, 12].

**TABLE IV**

<table>
<thead>
<tr>
<th>MATERIAL</th>
<th>(\rho) (kg/m(^3))</th>
<th>(C_0) (m/s)</th>
<th>(S)</th>
<th>(\Gamma_0)</th>
</tr>
</thead>
<tbody>
<tr>
<td>WATER</td>
<td>1000</td>
<td>1490</td>
<td>1.79</td>
<td>1.65</td>
</tr>
<tr>
<td>A2024</td>
<td>2770</td>
<td>3900</td>
<td>1.5</td>
<td>1.3</td>
</tr>
</tbody>
</table>

III. RESULT AND DISCUSSION

A. Study of Shock Wave Propagation

Fig2 shows pressure contours of water elements. According to this figure a shock wave has been produced by explosion under the water in time between 5\(\mu\)s to 10\(\mu\)s and has started its spherical propagation. After 15\(\mu\)s, arrives in the middle of blank and the reflective wave is produces. This is completely visible after 20\(\mu\)s. The pressure produced by this wave rapidly drops at this moment. The wave produced by explosion cause the drawing the aluminium blank to 50mm depth. Forming of the blank goes to an end after 400\(\mu\)s.

B. Study of Forming Process

The rate of aluminium plate deformation was shown in fig3. The time in this figure is between “0 to 400 micro second”. The curve related to this forming process was shown in fig4 as well. As it is obvious from fig3 and 4 the most deformation is between “10 to 25 micro second” and Strain rate became less after that the most available elongation. Using the explosive forming method; the maximum depth of drawing is 30.2, it is obvious from fig4.

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\(^1\) Jones – Wilkins - lee
Fig. 3 The rate of aluminium plate deformation

Fig. 4 The curve related to aluminium forming process

C. Experimental and Theoretical Conclusions Comparison

The comparison between simulation and experimental conclusion was brought in Table 5

<table>
<thead>
<tr>
<th>Method</th>
<th>Maximum depth of drawing</th>
</tr>
</thead>
<tbody>
<tr>
<td>Deep drawing (experimental)</td>
<td>15.4 mm</td>
</tr>
<tr>
<td>Hydro forming (experimental)</td>
<td>19.1 mm</td>
</tr>
<tr>
<td>Explosive forming (experimental)</td>
<td>25.8 mm</td>
</tr>
<tr>
<td>Explosive forming (numerical)</td>
<td>30.2 mm</td>
</tr>
</tbody>
</table>

According to that table the most elongation in hydro forming, deep drawing and explosive forming methods was studied and their conclusions of their simulation were compared. In all mentioned in Table 5 test; plate materials A2024, the blank primary diameter 100mm, the die cavity diameter 50mm and the plate thickness in all models is 1mm. According to table 5 information the most available elongation in hydro forming method had increase 24%, compared with deep drawing method. But this parameter had increasing in explosive forming method compared with deep drawing method 67% and hydro forming method 35%. The reason of this elongation increase in explosive forming methods compared with other methods can be mostly related to decreasing of friction effects, work hardening and increasing in effective strain rate. Although the error coming out of numerical methods in comparison with experimental method is 17%. That is ignorable according some factors in experimental methods such as spring back.

IV. CONCLUSION

Available elongation in free explosive forming is more considerable in comparison with similar methods. The increase in elongation can happen because of following reasons: The live out friction effects between punch and work piece that doesn’t exist in the explosive forming method. Because the mentioned factors lead to increase in she stress in aluminium plate and consequently precocious fracture. This effect goes down in hydro forming method because hydrostatic stress on plate. The decrease of work hardening and spring back effects due to high strain rate. Numerical methods in this article seem so trustable and affective because of low errors in comparison with experimental date.

REFERENCES

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