Origami Theory and its Applications: A Literature Review

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Abstract—This paper presents the fundamentals of Origami engineering and its application in nowadays as well as future industry. Several main cores of mathematical approaches such as Huzita-Hatori axioms, Maekawa and Kawasaki’s theorems are introduced briefly. Meanwhile flaps and circle packing by Robert Lang is explained to make understood the underlying principles in designing crease pattern. Rigid origami and its corrugation patterns which are potentially applicable for creating transformable or temporary spaces is discussed to show the transition of origami from paper to thick material. Moreover, some innovative applications of origami such as eyeglass, origami stent and high tech origami based on mentioned theories and principles are showcased in section III; while some updated origami technology such as Vacuumatics, self-folding of polymer sheets and programmable matter folding which could potentially applicable for creating transformable or temporary spaces are demonstrated in Section IV to offer more insight in future origami.

Keywords—Origami, origami application, origami engineering, origami technology, rigid origami.

I. INTRODUCTION

ORIGAMI is the art of paper folding originated from Japan and has been commonly practiced worldwide. It derived its name from the Japanese word ‘oru’ as in ‘to fold’, and ‘kami’ as in ‘paper’. Whenever origami is mentioned, first thing comes in people mind might usually be ‘paper crane’ or even ‘children activity’. It conventionally perceived as just a kind of art rather than something offer practical usage. Over the years, origami has intrigue many artists and scientist to investigate and reveal its underlying principles. These ultimately lead to the transition of origami from art to mathematical world. Since then origami technique has been utilized in many industry applications and proven to be useful in areas such as architecture and packaging design.

II. ORIGAMI SCIENCE

A. The Fundamentals

Origami originated as a trial-and-error art design for making paper(s) to appear like real object by folding them. Later on several mathematical approaches were developed to understand the phenomena on the paper generated by the folding and also to estimate the outlook of the origami (folded paper).

Prior to the theories, there are some common notations or terms in origami which should be acknowledged. These have been standardized by scientists, to name a few, including Lang, Huffman, Clowes, Waltz, Takeo Kanade, and Akira Yoshizawa [1] & [2]. In summary, the notations being widely used in the Origami practice are Mountain fold (fold the paper behind), Valley fold (fold the paper toward you), Crease (location of an earlier fold, since unfolded), X-ray line (hidden edge or crease), and Crease pattern (all the crease lines, since unfolded). While the basic folding patterns in the industry are the Cupboard Base, Windmill Base, Waterbomb Base, and Preliminary Fold [1].

Mathematical approaches for Origami, to name a few, are Geometry, Topology (explained by Thomas Hull [1]), Robert Lang’s Tree Theorem [2] and Maekawa’s String-to-beads method [3].

The mentioned mathematical approaches are surrounding three main fundamentals: Huzita-Hatori axioms, Maekawa and Kawasaki’s theorems.

Firstly discovered by Jacques Justin in 1989, the Huzita-Hatori axioms consist of 7 axioms were improved by Humiaki Huzita in 1991, and finalized by Koshiro Hatori, Justin and Robert Lang in 2001. The axioms [4] are:

1. Given two points P1 and P2, there is a unique fold that passes through both of them.
2. Given two points P1 and P2, there is a unique fold that places P1 onto P2.
3. Given two lines l1 and l2, there is a fold that places l1 onto l2.
4. Given a point P1 and a line l1, there is a fold that places P1 onto l1.
5. Given two points P1 and P2 and a line l1, there is a fold that places P1 onto l1 and passes through P2.
6. Given two points P1 and P2, and two lines l1 and l2, there is a fold that places P1 onto l1 and P2 onto l2.
7. Given one point P1 and two lines l1 and l2, there is a fold that places P1 onto l1 and is perpendicular to l2.

As simple as the axioms above, Maekawa’s theorem takes action in any origami model crease pattern as long as the paper folds flat. Looking at a single vertex (a point where multiple creases line come across) in the paper’s interior of a flat origami crease pattern, the difference between the number of mountain creases (M) and valley creases (V) must always be 2 as shown in (1).

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There is another famous result that relates the angles between the creases surrounding a vertex and is named after Toshikazu Kawasaki. The Kawasaki Theorem has proven that for a given crease pattern is foldable only if all the sequences of angles surrounding each (interior) vertex can be summed to 180° as given in eq. (2) and eq. (3) and represented in Fig. 1 [5].

\[ \alpha_1 - \alpha_2 + \alpha_3 - \alpha_4 + \cdots - \alpha_{2n} = 0^\circ \] (2)

Or another way of saying

\[ \alpha_1 + \alpha_3 + \cdots + \alpha_{2n-1} = \alpha_2 + \alpha_4 + \cdots + \alpha_{2n} = 180^\circ \] (3)

According to Lang [2], there are 3 types of flaps: corner, edge and middle flaps as given in Fig. 2. The names of the flap come after the location of the tip of the flap falls on the square. Flaps are distinguished to determine the amount of material used in folding. Middle flap consumes the most part of a material as compared to corner flap which consumes the least amount of material. To prove this, Lang proposed that each the tips (of the flaps) forms the centre of a circle on a flat material.

Lang suggested that all circles surrounding the tips, may it be quarter-circle (for corner flap), semi-circle (for edge flap), or full circle (for middle flap), the radius of the circle is determined by the length of the flap, \( L \). Lang commented, “The amount of paper consumed doesn’t depend on the angle of the tip of the flap, only its length and location.” Thus, circles-packing where circles do not overlap each other, is used in determining the sizes of the circles – the size of the flap. This approach is seem to be essential in Rigid Origami, as hard materials in engineering applications are not capable to recover from the crease formed by folding.

**B. Rigid Origami**

Rigid origami applies in folding materials with thickness. Car airbags, large solar panel arrays for space satellites (using Miura-fold), paper shopping bags are amongst the studies in Rigid origami.

Having thickness in the material has disabled some fundamentals of origami in Rigid Origami such as Huzita-Hatori axioms. However, Kawasaki’s Theorem and Haga’s Theorem are still valid in real material folding [7].

Tomohiro Tachi mentioned in his research that Rigid origami consists of rigid panels connected by hinges constrained around vertices [8]. The origami configuration is represented by fold angles between the adjacent panels [9]. Intensive Mathematical model for 3D folding was presented in his paper [8] and it was used in his written software RigidOrigami.

Britney Gallivan has developed a loss function for origami folding with thick material and the function sounds like eq. (4).

\[ L = \frac{n \pi}{6} (2^n + 4)(2^n - 1) \] (4)

Where \( L \) is the minimum length of the material, \( t \) is the thickness of the material, and \( n \) is the number of folds possible [9].

It appears that there is no direct connection between Lang’s Tree Theorem and Tachi’s Rigid Origami. However, the former could be used in designing the folding based on a desired final outlook of an origami where else the latter could provide calculations on the folding mechanisms with materials with thickness.

**III. ORIGAMI APPLICATIONS**

**A. Solar Panels**

Origami concepts were used to pack and deploy a solar power array in the research vessel called Space Flight Unit (SFU) as shown in Fig. 3. The method of folding is called “Miura-ori” which had been introduced in last section.

**B. Space Telescope, Eyeglass**

The Eyeglass is a foldable telescopic lens designed by Robert Lang which can be easily packed into a space shuttle
and deployed when in space by utilizing origami principals and techniques.

The origami structure shown in Fig. 4 is called the “Umbrella” structure after its resemblance to a collapsible umbrella, which was scalable and had mass-producible parts. In 2002, a 5-meter prototype, as shown in Fig. 4, comprising 72 segments patterned with binary Fresnel arcs in photoresist was completed and shown to concentrate light as expected [11].

It was believed that a 25-meter or larger version diffractive space telescope could be deployed within a decade [11] while the ultimate goal might be folding a 100-meter lenses into 3-meter diameter cylinders [12].

C. Origami Stents for Medical Purposes

An origami stent was developed which may be used to enlarge clogged arteries and veins. The design followed waterbomb base origami style which enables it to be collapsed into a smaller size while travelling in veins/arteries, and expanded to a larger diameter at the clot site to serve its purpose (Fig. 5). The patterns are made from three type of folds: two sets of helical folds orthogonal to each other and cross folds. The existence of long helical folds enables a highly synchronized deployment process [13].

D. High Tech Origami

Researchers from University of Illinois have developed a technique to fold microscopically thin slice of silicon into different kinds of shapes (three-dimensional) which could be useful in many areas, including solar energy. They intended to design a spherical solar cell which claimed to be able to absorb solar energy more efficiently than a typical flat solar cell.

As shown in Fig. 6, a two-dimensional piece of silicon was cut into a flower shape with a small piece of glass planted in the center to help retaining the eventual desired shape. It was followed by placing a water droplet in the center of the silicon flower. As the water evaporates, capillary forces pulled the edges of the foil together to form the sphere shape [15][16].

The new self-assembly process is still in its early stage; however it shows a completely different approach to making three-dimensional structures.

E. Origami Grocery Bag

A foldable grocery bag from steel was built by Zhong You and Weina Wu using origami-inspired design as shown in Fig. 7. It allowed shopping bag built from a rigid material or an open-topped cardboard box could be folded flat without having its bottom opened. This approach could help speed up factory automated packaging processes. The ultimate dream of the designers is to make rigid building that could be reconfigured in the future [17][18].

IV. ADVANCEMENT OF ORIGAMI

A. Vacuomatics

Multi-DOF rigid foldable structures based on triangle panels is able to follow the change in the environment and human activities due to its flexibility. Vacuomatics is a solution to make the 3D form becomes geometrically stable by stiffening the dihedral hinges. The structural system is a negative pressured double membrane containing aggregate particles. It is initially plastic or viscoelastic, but by introducing negative pressure, the induced friction force between compressed particles makes the structure stiff [19].
Another interesting aspect of the structure is the particles can reconfigure themselves to be in another equilibrium state which therefore enables the strength of hinge to be controlled regarding the amount of vacuum. The example of Vacumatics is demonstrated in Fig. 8.

![Fig. 8 Hinge design: (a) Particles are placed in between panels. (b) Self-folding moment is induced by the vacuum (c) The vacuum keeps the hinge stiff (figure adopted from [19])](image)

### B. Self-Folding of Polymer Sheets

A technique was developed by Michael Dickey where polymer sheets self-fold when exposed to light as shown in Fig. 9. Polymer sheets were run through a desktop printer to get a pattern of black lines, or crease pattern in origami, and they automatically fold along the black lines when exposed to light. The concept is such that black absorbs more energy than other colours and thus black lines will shrink faster than other areas.

![Fig. 9 Polymer sheets with black lines (figure adopted from [12])](image)

### C. Programmable Matter Folding

Robert Wood and his team at Harvard University and the Massachusetts Institute of Technology have combined a thin sheet with programmable joints which flex in response to electrical warming [20]. The sheet is a kind of variable ‘programmable matter’ which developed by chemists specialized in molecular self-assembly and by robotics engineers working on ‘self-reconfiguring’ robots. Above all, Wood’s team has to first create an algorithm for folding with a dictated set of creases based on the desired end shapes. Then the hinged ‘actuators’ were located at each crease that open and close on command. The hinges are made of Nitinol, a ‘smart’ metal alloy of nickel and titanium which has the ability to return to its initial shape after being warmed and then bent.

![Fig. 10 A self-folded experimental ‘boat’ (figure adopted from [21])](image)

Their current prototype, shown in Fig. 10, used one-way switch as their hinges which must be bent back by hand. The hinges are stapled into a sheet made from triangular panels of stiff fiberglass where their edges are joined by flexible silicone rubber. There is a magnet sit in the middle of each panel which holds them firmly but not irreversibly together when they are folded face to face.

To initiate the on-demand folding, the team intended to develop removable ‘stickers’ which contain the circuitry specific to a particular folded shape therefore granting a given sheet to fold without the need of computer control over the hinge-heating process.

### V. CONCLUSION AND FUTURE WORKS

This paper has presented the fundamentals of Origami science, Rigidorigami and some of its applications. It is in hope that one could gain more insight about origami technology and apply it in every possible area for sustainable utilization of space and weight.

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### REFERENCES


