Effects of Natural Frequency and Rotational Speed on Dynamic Stress in Spur Gear

Ali Raad Hassan, G. Thanigaiyarasu, and V. Ramamurti

Abstract—Natural frequencies and dynamic response of a spur gear sector are investigated using a two dimensional finite element model that offers significant advantages for dynamic gear analyses. The gear teeth are analyzed for different operating speeds. A primary feature of this modeling is determination of mesh forces using a detailed contact analysis for each time step as the gears roll through the mesh. Transient mode super position method has been used to find horizontal and vertical components of displacement and dynamic stress. The finite element analysis software ANSYS has been used on the proposed model to find the natural frequencies by Block Lanczos technique and displacements and dynamic stresses by transient mode super position method. A comparison of theoretical (natural frequency and static stress) results with the finite element analysis results has also been done. The effect of rotational speed of the gears on the dynamic response of gear tooth has been studied and design limits have been discussed.

Keywords—Natural frequency, Modal and transient analysis, Spur gear, Dynamic stress.

I. INTRODUCTION

Rotating members like shafts, pulleys, gears, etc are subjected to dynamic loads. In gears the dynamic load creates bending stresses at the tooth root which can lead to fatigue failure. One of the major concerns in the design of power transmission gears is the reduction of dynamic load. Research work has revealed that the basic mechanism of noise generated from gears is due to vibration excited by the dynamic load. The life and reliability of a gear transmission is reduced by high dynamic load. Minimizing gear dynamic load will decrease gear noise, increase efficiency, improve pitting fatigue life, and help prevent gear tooth fracture. The authors from [1] to [7] work in the area of static and dynamic analysis of spur gear tooth. In this work, three tooth segment of a 30 tooth pinion meshing with 60 tooth gear has been considered. Trochoid fillet at the base of the involute tooth is generated using rack tip.

II. GEAR TOOTH GEOMETRY

Review Stage The pinion has a pitch diameter of 750mm, module of 25mm and a nominal pressure angle of 20 degree. The pinion has standard full depth teeth with addendum of 1.0 m and dedendum of 1.25 m. The face width of the pinion is 60mm. A 28000N load is considered along the line of action of the model. Development of the finite element model begins with data describing the outline of a single tooth and its fillets from the center of the tooth space on one side to the center of the tooth space on the other side. Several different curves make up the tooth outline: concentric circular arc at the tooth tip defining the addendum circle, involutes on the two sides of the tooth, and trochoides between the involutes and the bottom lands at the base of the tooth. The tooth side involutes, fillet trochoides, and bottom lands were shaped to model a gear cut with a rack form cutter. Coordinates for the surface profile of the tooth come from a kinematic analysis of the cutting process [8]. Both the rack form cutter and the resulting gear surface are tangent to each other at the cutting points, which generate the gear shape from the rack shape. The involute is generated by points on the side of the rack form, the gear tooth fillet is generated by the tip of the rack form, and the bottom land is generated by the top surface of the rack form tooth. With the appropriate rotations, this slope and radius locates the direction and point of application of the gear mesh force on the central tooth. For this mesh, the gear parameters

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Unit</th>
</tr>
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<tbody>
<tr>
<td>t</td>
<td>Tooth thickness</td>
<td>mm</td>
</tr>
<tr>
<td>M</td>
<td>Bending moment</td>
<td>N-mm</td>
</tr>
<tr>
<td>ra1</td>
<td>Outer radius of pinion</td>
<td>mm</td>
</tr>
<tr>
<td>ra2</td>
<td>Outer radius of gear</td>
<td>mm</td>
</tr>
<tr>
<td>rb1</td>
<td>Base radius of pinion</td>
<td>mm</td>
</tr>
<tr>
<td>rb2</td>
<td>Base radius of gear</td>
<td>mm</td>
</tr>
<tr>
<td>P</td>
<td>Full load</td>
<td>N</td>
</tr>
<tr>
<td>P0</td>
<td>Base pitch</td>
<td></td>
</tr>
<tr>
<td>Z</td>
<td>Number of teeth</td>
<td></td>
</tr>
<tr>
<td>φ</td>
<td>Pressure angle</td>
<td>degree</td>
</tr>
<tr>
<td>σx</td>
<td>Stress in X-direction</td>
<td>MPa</td>
</tr>
<tr>
<td>σy</td>
<td>Stress in Y-direction</td>
<td>MPa</td>
</tr>
</tbody>
</table>

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used are: module (m) 25mm, the pressure angle (\(\phi\)) 20 degrees, gear ratio (i) 2, modulus of elasticity (E) \(2.15 \times 10^5\) N/mm², poisson’s ratio (v) 0.3, Steel mass density (\(\rho\)) \(8.75 \times 10^{-9}\) N.s²/mm⁴ and the speed (N) 1440 rpm.

III. NATURAL FREQUENCY CALCULATION

Fig. 1 shows the gear tooth as a cantilever beam. It is easy to calculate the natural frequency of this beam by the following equation [10]:

\[
\omega_n = \sqrt{\frac{k}{\text{mass}}} 
\]

(1)

k is the stiffness of the beam and it can be calculated from the following equations:

\[
k = \frac{3EI}{l^3}
\]

(2)

\[
l = \frac{F \times t^3}{12}
\]

(3)

The length of the beam \(l\) is equal to the height of the tooth while the width of the beam \(t\) is the tooth thickness at pitch circle radius (\(\pi m/2\)).

\[
\text{mass} = \rho(l \times t \times F)
\]

(4)

Where, \(\rho\) is the mass density of Steel and F is the tooth face width. By using the above formula, the natural frequency is calculated using the equation (1) and is equal to 44600 rad/sec.

IV. NATURAL FREQUENCY BY RAYLIEGH’S METHOD

Rayleigh’s method can also be used to find the natural frequency of continuous systems. This method is much simpler than exact analysis for systems with varying distribution of mass and stiffness. Although the method is applicable to all continuous systems, it is applied to beam in this section; the natural frequency by this theory is [13]:

\[
\omega_n^2 = \frac{\int_0^l E I \left( \frac{d^2u(x)}{dx^2} \right) dx}{\int_0^l \rho \rho u(x)^2 dx}
\]

(5)

The shape function \(u(x)\) of cantilever beam can be taken as [10]:

\[
u(x) = C_1 \left( \frac{x^3}{l} - \frac{5x}{l} + 4 \right)
\]

(6)

By substituting Eq. (6) in Eq. (5) and applying the required gear details of the selected model, the resulting value of the natural frequency is 50968 rad/sec.

V. STRESS CALCULATION

The load acting during the entire period of engagement is not uniform. In the beginning, at the start of engagement, two pairs of teeth will be in contact and it is assumed each pair will carry only half of the load, and the contact point will be in the tip of one of these teeth, but due to rotation, during the engagement, a new stage of contact is effected when a single pair of teeth is in contact near the pitch circle. This is called a single tooth contact and the first point of contact of this new stage is called the highest point of single tooth contact (HPSTC). Hence, loads equal to 28000N (total load) are applied to the end of the cantilever beam at an angle equal to the pressure angle of the two mating gears, namely 20 degrees. The height of the beam \(l\) will be assumed to be the distance between the pitch radius and root radius of the gear. The axial and radial components of this load are taken as the X-direction and Y-direction components of the load at a point corresponding to the pitch radius of the cantilever beam where the load is full value, which are 26311.4N, 9576.5N respectively. The stresses in X and Y directions can be calculated by the following equations:

\[
\sigma_x = \frac{P \sin \phi}{F_x} 
\]

(7)

\[
\sigma_y = \frac{P \cos \phi \times 1}{F_y} 
\]

(8)

Where, \(t\) is the thickness of the tooth at the critical section (root of the tooth), F is the face width of the tooth, P is the total load and \(\sigma_x\) and \(\sigma_y\) are the maximum stresses of the beam in X and Y axes respectively. From this formulation, the obtained value of stress in X direction for the proposed model is 1.95 MPa, and the stress in Y direction is 39.006 MPa respectively.

VI. FINITE ELEMENT MODEL

A model consisting of a three tooth section of a 30 tooth of 25mm module pinion was developed with the general purpose finite element software ANSYS. Figs. 2 show the finite element grid for the three tooth gear segment for this model. Successive reflections of the coordinates for the initial tooth generated segments of three equally spaced, identical teeth are noted. Both the tooth surface and the inside rim surface are unconstrained. The total angle subtended by the segment is 35 degrees.
VII. MODAL ANALYSIS

Having obtained the finite element model, a modal analysis has been conducted on the same. The global stiffness matrix \( [K] \) and global mass matrix \( [M] \) was obtained by assembling the element stiffness and mass matrices, respectively. The natural frequencies of the gear tooth were obtained by solving the eigen value problem given by the following equation:

\[
[K][U] = \omega_n^2[M][U]
\]

where \( \omega_n \) is the natural frequency of the system and \( \{U\} \) is the corresponding normalized eigen vector (mode shape). The eigen values and eigen vectors were obtained using Block Lanczos method. The first five natural frequencies and corresponding normalized eigen vectors were calculated using this technique. The first five natural frequencies of the gear tooth obtained for the selected model are given in Table 1.

### TABLE 1

<table>
<thead>
<tr>
<th>Mode</th>
<th>Natural frequency of the model</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>cycle/sec</td>
</tr>
<tr>
<td>1</td>
<td>7.342</td>
</tr>
<tr>
<td>2</td>
<td>7.647</td>
</tr>
<tr>
<td>3</td>
<td>7.947</td>
</tr>
<tr>
<td>4</td>
<td>10.497</td>
</tr>
<tr>
<td>5</td>
<td>12.662</td>
</tr>
</tbody>
</table>

VIII. LOAD DISTRIBUTION ON GEAR TOOTH

Load distribution on gear tooth In order to conduct a static stress analysis the loads have to be evaluated. The load on the central tooth of the finite element model, which produces the largest bending stress, is the full load acting at the highest point of single tooth contact (HPSTC). The magnitude of load at any point of contact on profile of gear tooth as the load moves from root to tip of tooth depends on the contact ratio. Fig. 4 shows the contact path, the contact ratio \( C_r \) is defined as the ratio of length of path of contact \( AB \) to base circle pitch \( P_b \).

\[
C_r = \frac{\overline{AB}}{P_b}
\]

Where:

\[
\overline{AB} = \sqrt{r_{a1}^2 - r_{b1}^2} + \sqrt{r_{a2}^2 - r_{b2}^2} - (r_{b1} + r_{b2}) \tan \phi
\]

The contact ratio of the spur gear, for the present case is 1.7.
Fig. 4 Contact path

Fig. 5 shows the magnitude of loads at various points along the path of contact. The maximum normal load $P$ acting on the gear tooth sector of the proposed model is taken as 28000N based on the strength of gear tooth material. This normal load is considered in terms of its components in radial and tangential directions taking into account the pressure angle ($\gamma_w$) at any point under consideration, and then the tangential load and radial load can be determined by the following equations:

$$P_t = P \cos \gamma_w$$
$$P_r = P \sin \gamma_w$$

Fig. 5 Magnitude of loads along the path of contact

Fig. 6 show the right side (Tension side) of the profiles of the central tooth of the selected model, shown in Fig. 3, stretched out into straight line with the nodes indicated for the purpose of application of loads. The load that have been applied for the various runs of static analysis are indicated on the respective nodes starting from the extreme left end (node 52) to the final point of contact (node 58) of the model.

IX. STATIC BENDING STRESS ANALYSIS

A quasi-static analysis has been carried out to determine the maximum static stress in the gear tooth for the moving load. The governing equation is expressed as:

$$[K] \{\delta\} = [P]$$

(12)

The moving load during the time of contact is considered in 9 intervals. At each time interval, the position and magnitude of the load is different and shown in Table 2. The static stress on all the elements for each load is obtained by using ANSYS Finite Element software and the static bending stresses on the critical nodes (Node 102) on the compression side are listed in the same table.

<table>
<thead>
<tr>
<th>Load</th>
<th>Load Applied on Nodes</th>
<th>Stress at node 102 (MPa)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>52 Half</td>
<td>6.824 45.302</td>
</tr>
<tr>
<td>2</td>
<td>72 Half</td>
<td>6.125 42.799</td>
</tr>
<tr>
<td>3</td>
<td>70 Half</td>
<td>6.429 40.301</td>
</tr>
<tr>
<td>4</td>
<td>68 Full</td>
<td>12.312 55.686</td>
</tr>
<tr>
<td>5</td>
<td>66 Full</td>
<td>5.828 49.727</td>
</tr>
<tr>
<td>6</td>
<td>64 Full</td>
<td>4.009 39.360</td>
</tr>
<tr>
<td>7</td>
<td>62 Half</td>
<td>3.525 29.873</td>
</tr>
<tr>
<td>8</td>
<td>60 Half</td>
<td>3.121 27.812</td>
</tr>
<tr>
<td>9</td>
<td>58 Half</td>
<td>2.533 24.955</td>
</tr>
</tbody>
</table>

X. TRANSIENT ANALYSIS

After computing the natural frequencies and the mode shapes the forced response is obtained using the modal superposition technique [11]. The method is computationally efficient particularly for a large sized problem. The governing differential equation of gear tooth considering the damping is:

$$[M][\ddot{\delta}] + [C][\dot{\delta}] + [K][\delta] = \{P(t)\}$$

(13)

Where $[M]$, $[C]$ and $[K]$ are global mass, damping and stiffness matrices of size ($n\times n$), respectively. The $\{P(t)\}$ is the external time varying load of size ($n\times1$). The symbols $\{\delta\}$, $\{\dot{\delta}\}$, $\{\ddot{\delta}\}$ are the displacement, velocity, acceleration vectors of size ($n\times1$). Eq.(13) has to be recast such that m uncoupled equations in a single degree may be obtained. The recast equation can be obtained by substituting for $\{\delta\}$, as $\{\delta\} = [U]\{p\}$, where $[U]$ is a matrix (size $n\times m$) of the first m
One time step $\Delta T$ can be calculated by considering the number of modes, which are expected to contribute to the dynamic response. So, the third frequency of the model is (7947 cycle/sec) which is taken from the finite element modal analysis results in Table 1; the time interval obtained is (1.258×10^-5 sec) and is shown in Fig. 6. If the natural period of the mth mode is $T_m$, a choice of $\Delta T$ equal to $T_m/10$ should give a reasonable dynamic response up to mth mode [11]. Therefore,

$$\text{TNTS} = \frac{60}{\Delta T N \cdot Z}$$  \hspace{1cm} (19)

Where, TNTS is the total number of time steps or intervals. So, the total number of intervals (time steps) for the model is 110 which mean that there are about 13 intervals between each two nodes shown in Fig. 6. At any time, two nodes are considered to calculate the load vector for that time interval. The actual load at a point is distributed in inverse proportion to its distance from either node, to the two nodes under consideration as shown in Fig. 6. The Initial conditions for displacements and velocities for the gear tooth in the proposed model are taken as zero for all degrees of freedom. The third mode is selected for the mode superposition technique. At each time interval, the acting load is calculated and fed into the mode superposition part in ANSYS software and the corresponding deformation and stress are thus obtained. The dynamic displacements and dynamic stresses in the X and Y directions of the selected model, which are at node 102, are plotted in condition of 1440 rpm. The dynamic analysis is also carried out for the following four speeds of gear namely, 360 rpm, 720 rpm, 1440 rpm and 1800 rpm.

XI. RESULTS

Figs. 7 and 8 show the dynamic displacements in the X and Y directions of the selected model at node 102. Figs. 9 and 10 show the dynamic stresses at X and Y directions of the model at node 102. Figs. 11 and 12 show the dynamic shear stress and dynamic von Mises stress of the model at node 102.
Table 3 lists the Maximum values of $\sigma_X$, $\sigma_Y$, $\tau_{xy}$ and von Mises stresses of the model at node 102 for different speeds, where Figs. 13, 14 and 15 show the relation curves of $\sigma_X$, $\sigma_Y$ and von Mises stresses with the rotational speeds, respectively.

<table>
<thead>
<tr>
<th>Speed (rpm)</th>
<th>$\sigma_X$ (MPa)</th>
<th>$\sigma_Y$ (MPa)</th>
<th>$\tau_{xy}$ (MPa)</th>
<th>von Mises (MPa)</th>
</tr>
</thead>
<tbody>
<tr>
<td>360</td>
<td>15.911</td>
<td>55.434</td>
<td>24.992</td>
<td>65.711</td>
</tr>
<tr>
<td>720</td>
<td>18.308</td>
<td>70.898</td>
<td>30.027</td>
<td>82.272</td>
</tr>
<tr>
<td>1440</td>
<td>22.103</td>
<td>90.624</td>
<td>39.113</td>
<td>106.244</td>
</tr>
<tr>
<td>1800</td>
<td>23.622</td>
<td>97.247</td>
<td>40.191</td>
<td>112.089</td>
</tr>
</tbody>
</table>
time period was calculated for each of the above plots. The frequency of the response, in cycles per seconds, can be calculated by dividing the number of peaks for a selected time period by the time taken for the same. For example: at Fig. 10 (which shows the dynamic stress of the model in Y-direction) for time period (0 to $0.417 \times 10^{-3}$ sec) the number of peaks was 3, so; the resulting frequency was calculated by dividing 3 on $0.417 \times 10^{-3}$ sec, which yields (7194 cycle/sec). It was clear that this value matches with fundamental natural frequency of the model (first natural frequency of the model in Table 1).

XII. DISCUSSION

The natural frequency of the tooth obtained by Rayleigh’s method (Eq. 5) using which is was 50968rad/sec. The natural frequency obtained by beam formulation (Eq. 1) was 44600rad/sec. It was noted in Rayleigh’s method that the assumed shape u(x) unintentionally introduces a constraint on the system (which amounts to adding additional stiffness to the system), and hence the frequency given by Eq. (5) is higher than the exact value. The natural frequency obtained from Eq. (1) is more reasonable and recommended. The first natural frequency obtained from finite element modal analysis was 46135rad/sec. There is a good agreement between this value and the recommended natural frequency value obtained from Eq. (1). It was observed from the plots (shown in Figs. 9 and 10) that the dynamic stresses were varied with a time period of $1.39 \times 10^{-4}$sec whereas the time period of the fundamental natural frequency was $1.36 \times 10^{-4}$sec. The dynamic stress plots at tooth root where (shown in Figs. 9 and 10) and deformation at the tooth root were (shown in Figs. 7 and 8). Three important distinguishable regions were observed. In the first region the displacements and dynamic stresses during starting of engagement of the gear tooth were zero, and both the pairs of teeth were contact and share normal load equally. In the second region, displacements and dynamic stresses were high compared to all other regions, in this region, a single pair of gear tooth will be in contact and full load act on the gear pair under study. In the third region again, two pairs of gear teeth were in contact and share load equally. From the dynamic analysis results, the dynamic stresses at the root are lesser when the load was at the tip, and were high when the load was at the mid height [that is at HSPTC- the highest point of single tooth contact] at this point the full load was acting. From the static analysis, the maximum values of $\sigma_X$ and $\sigma_Y$ were at node 102 of the model lie in the root at left side (compression side) of the central tooth. For the actual load distribution on the gear profile obtained by finite element method the stresses $\sigma_X$ and $\sigma_Y$ were 12.312MPa and 55.686MPa, respectively, when full load is at HSPTC point (node 68). By beam gear design approach the values of $\sigma_X$ and $\sigma_Y$ calculated from Eqs.7 and 8 were 1.95MPa and 39.006MPa, respectively. This shows good agreement between these values if the differences between the tooth and beam shapes are considered.
From the dynamic stress analysis stress plots at the root of the model (node 102; the maximum $\sigma_x$, $\sigma_y$, $\tau_{xy}$ shear stress and von Mises stress were 22.103MPa, 90.624MPa, 39.113MPa and 106.244MPa respectively.

![Fig. 16 Stress response of the 1st model in Y-Direction](Image)

Reframing to Figs. 9 and 10, it was observed that the magnitude of static stresses ($\sigma_x$ and $\sigma_y$) at the point of application was half of the enveloping curves of the dynamic stresses (mean of the maximum and minimum dynamic stresses). The amplitude of the dynamic stress goes on increasing as the speed increases with its major frequency of variation corresponding to the fundamental frequency of the gear tooth. This may be observed from Fig. 16.

It is observed from Tables 3 that the maximum magnitudes of $\sigma_x$, $\sigma_y$, $\tau_{xy}$ and von Mises stress at the tooth root for various speeds of the selected gear model (in the range of 360 rpm to 1800 rpm) were increasing gradually from 15.911MPa to 23.622MPa, from 55.434MPa to 97.247MPa, from 24.992MPa to 40.191MPa, and from 65.711MPa to 112.089MPa respectively, for increase in speed from 360rpm to 1800rpm. The variation is shown in Figs. 13, 14 and 15. Therefore, the dynamic stresses at the root of the high modules spur gear tooth were increasing with increase in the rotational speed of the gear.

A. Food for thought

Modal super position technique assumes that any transient disturbance of member is the sum total of the disturbances due to the first few modes of vibration. In reality the contribution from the higher modes die down very fast in comparison with the first mode. This has been experimentally observed to be true. It is found that as the rotational speed of gear increases, the bending stress of dynamic stress also increases. For the moving load, the ratio of maximum dynamic bending root stress to maximum static bending root stress is increases gradually as the rotational speed of gear increases.

XIII. Conclusion

Modal super position technique assumes that any transient disturbance of member is the sum total of the disturbance due to the first few modes of vibration. In reality the contribution from the higher modes die down very fast in comparison with the first mode. This has been experimentally observed to be true. It is found that as the rotational speed of gear increases, the bending stress of dynamic stress also increases. For the moving load, the ratio of maximum dynamic bending root stress to maximum static bending root stress is increases gradually as the rotational speed of gear increases.

**REFERENCES**


Dr. Ali Raad Hassan, Assistant Professor of Technical Institutes (Iraq), Chief Engineers at Ministry of Minerals and Industry (Baghdad). He has been awarded 5 times for his research and developments on gear manufacturing machines. Currently he got his PhD in mechanical engineering from Department of Mechanical Engineering, Anna University (India). He has two national journals papers publications, and he has many papers under reviewing at many international journals. He has about 10 years experience in Industry.

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