Abstract—Results of Chilean wine classification based on the information provided by an electronic nose are reported in this paper. The classification scheme consists of two parts; in the first stage, Principal Component Analysis is used as feature extraction method to reduce the dimensionality of the original information. Then, Radial Basis Functions Neural Networks is used as pattern recognition technique to perform the classification. The objective of this study is to classify different Cabernet Sauvignon, Merlot and Cármenère wines based on their seven years, varieties and vineyards of Chile.

Keywords—Feature extraction techniques, Pattern recognition techniques, Principal component analysis, Radial basis functions neural networks, Wine classification.

I. INTRODUCTION

During the last decade several papers have been written concerning wine classification using information supplied by an electronic nose.

In [1] an aromatic classification of three wines of the same variety but different years (1995, 1996 and 1997) is presented. The input data for classification is obtained from an electronic nose [2] based on six sensors of conducting polymers. For classification purposes a Multilayer Perceptron (MLP) trained with the backpropagation algorithm (BP) [3] and a Time Delay Neural Networks (TDNN) trained with the Levenberg-Marquardt algorithm [3] were used.

In [4] wine classification is done using a NN with data provided by an electronic nose built by the authors using sensor commercially available. These sensors are of tin oxide and use the principle of resistance variations due to the adsorption of gas molecules on its surface.

Recently, in [5] an electronic nose based on metal oxide semiconductor thin-film sensors has been used to characterize and classify four types of Spanish red wines of the same variety of grapes. Principal component analysis (PCA) and probabilistic neural network (PNN) were used obtaining good results.

In this paper a wine classification methodology based on neural techniques is proposed, using as input data gas chromatograms of Chilean red wines of the varieties Cabernet Sauvignon, Merlot and Cármenère. The gas chromatograms are provided by an electronic nose model Fast GC Analyzer 7100 built by Electronic Sensor Technology. The sensor used by this instrument is of the type surface acoustic wave (SAW).

The first stage of the proposed methodology is concerned with the dimension reduction of the patterns preserving the original information from classification viewpoint. This is done using the feature extraction method Principal Component Analysis (PCA) [6]. Once the dimension of the input data has been reduced the information pass to a classification stage where a technique based on radial basis functions neural networks (RBFNN) [6, 7] is used. The general scheme of the proposed methodology is shown in Fig. 1.

In Section II a brief description of the feature extraction and the classification techniques used in this study are presented. Section III is devoted to explain the methodology used in this work. The results obtained together with a discussion are presented in Section IV. Finally some conclusions are drawn in Section V.

II. BRIEF DESCRIPTION OF THE FEATURE EXTRACTION AND CLASSIFICATION TECHNIQUES

In this section we present a brief description of the feature extraction and classification (pattern recognition) techniques used in this study. The description of each technique is made only for completeness and for a more detailed description the reader is referred to the cited references.

A. Principal Components Analysis (PCA)

In the Principal Components Analysis (PCA) method the main idea is to transform the original feature space into one in which the data is not correlated. This new space is obtained by projecting the original data onto a set of orthogonal axes in which the variance of the input data is maximized. This technique can be summarized in the following theorem of the principal component analysis [6].

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Fundamental Theorem for PCA

Given a set of variables \( x_i \in \mathbb{R}^n \) for \( i = 1,2,...n \) with a non singular covariance matrix \( \Sigma_x \in \mathbb{R}^{n \times n} \), it is always possible to define a subset of non correlated variables \( y_i, y'_i \in \mathbb{R}^p \) for \( i = 1,2,...,n \), by means of a linear transformation \( W \), corresponding to a rigid rotation, whose columns are eigenvectors of \( \Sigma_x \). The covariance matrix of the new set of variables \( \Sigma_y \in \mathbb{R}^{p \times p} \), is diagonal and contains the eigenvalues \( \lambda_i \) for \( i = 1,2,... \) of \( \Sigma_x \) associated to the eigenvectors which are columns of \( W \).

Form the previous Theorem the eigen-values \( \lambda_i \) can be seen as the variance of the patterns in the transformed space, which are related to the range of the patterns of each axis of this space. On the other hand, the eigenvectors \( \phi_j \) associated to the eigen-values \( \lambda_i \) determine the direction of the axis of maximum variance. Thus selecting a subset of eigenvectors a rotation will be performed that align the transformed axes with the direction of the maximum variance of data. The dimension reduction will be determined by the size of the set of eigenvectors chosen.

In Section III E a detailed explanation is presented, as to how the PCA methodology is used in this particular case to reduce the dimension of the input data to the classifier.

B. Radial-Basis Functions Neural Networks (RBFNN)

When Pattern recognition techniques based on neural networks have shown a great behavior for a wide range of applications [6, 8] and they are very attractive since a minimum knowledge on the patterns is required. The radial-basis functions neural networks (RBFNN) constitute the main alternative to the multi-layer perceptron (MLP) for data interpolation and pattern classification problems. They are characterized since instead of using a linear activation function they use functions with symmetry around a center \( c \) in the \( n \)-dimensional space of the input patterns.

Each neuron in a RBFNN corresponds to a region in the \( n \) dimensional input space with center \( c \). The activation level of a neuron in a RBFNN to an input \( x \) is a function of the Euclidean distance between \( x \) and the center \( c \) of the neuron. The output of the neuron in a RBFNN is given by the general equation

\[
y^i(x) = \sum_{j=0}^{M} w_{ij} \phi_j(x)
\]

where \( \phi_j(x) \) are the RBF and \( w_{ij} \) are the weights in the output layer (See Fig. 3). The basis functions \( \phi_j(x) \) can be interpreted as the a posteriori probabilities \( p(C_k \mid j) \) of the members of a class given certain input characteristics. That is the reason why it is natural to apply RBFNN to pattern classification problems [8].

The usual way is to set the center \( c \) at each one of the training patterns of the problem. Thus, if we have \( p \) training patterns the network has \( p \) neurons centered at each pattern. This strategy guarantee zero error in the training set and the freedom to choose \( \sigma \) that generates a controlled spatial overlapping to guarantee a good generalization. Depending on
the computational implementation utilized, σ can be equal for all neurons or have different values for each unit.

The next step is to choose the weight vector \( w \in \mathbb{R}^m \). To this extent the RBFNN is evaluated at the \( p \) training patterns

\[
\phi_{ji} = \phi(||x_i - x_j||) \quad \forall i, j = 1...m
\]

(4)

where \( || \) corresponds to the Euclidean norm between two vectors.

We define matrix \( \Phi \) composed by all the \( \phi_{ji} \), as the interpolation Matrix of the problem [9], from which the weights can be obtained through the relationship

\[
\Phi w = T
\]

(5)

where \( w \in \mathbb{R}^m \) is the weight vector and \( T \in \mathbb{R}^m \) is the objective vector (target) containing the desired outputs.

Then if \( \Phi \) is nonsingular the weights are obtained as

\[
w = \Phi^{-1} T
\]

(6)

The Michelli’s Theorem [9] guarantee that if all vectors \( x_i \) used to compute \( \Phi \) are all different, then \( \Phi \) will be nonsingular.

III. EXPERIMENTAL SETUP

A. Electronic Nose

If the electronic nose used in the study is the model Fast GC Analyzer 7100 built by Electronic Sensor Technology [13] with surface acoustic wave (SAW) sensor. The most important operating parameters for the electronic nose are:

- Sensor: Temperature of the SAW detector in °C
- Column: Temperature of the column GC in °C
- Valve: Temperature of the six position valve in °C
- Inlet: Temperature of the input gas in °C
- Trap: Temperature of the trap in °C
- Ramp: Value of the temperature ramp in °C/sec

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sensor</td>
<td>60</td>
<td>°C</td>
</tr>
<tr>
<td>Column</td>
<td>40</td>
<td>°C</td>
</tr>
<tr>
<td>Valve</td>
<td>140</td>
<td>°C</td>
</tr>
<tr>
<td>Inlet</td>
<td>175</td>
<td>°C</td>
</tr>
<tr>
<td>Trap</td>
<td>300</td>
<td>°C</td>
</tr>
<tr>
<td>Ramp</td>
<td>10</td>
<td>°C/sec</td>
</tr>
</tbody>
</table>

This set of parameters defines the method under which operates the instrument. After a series of tests and experiments it was determined that the best values of the parameters for our study are those shown in Table I. These values were set on the instrument to perform all the analyzes of the wine samples to generate the databases used in this study.

With respect to the wine samples, several Cabernet Sauvignon, Merlot and Carménère commercial Chilean wines were analyzed. 40 [ml] were introduced into a 60 [ml] vials with septa caps trying to avoid the contact of the sample with the oxygen. The measurements were done immediately after the bottle was opened, maintaining the room temperature at 20 °C. Figure 4 shows a photograph of the electronic nose during the measurement of a wine sample.

B. Database

The database used in the study is formed by 100 commercial samples of Chilean wines of the type Cabernet Sauvignon, Merlot and Carménère. These wines belong to the vintages 1997-2003 and come from different valleys of the central part of Chile. The distribution of the samples is shown in Table II.

<table>
<thead>
<tr>
<th>Class</th>
<th>Type</th>
<th>Number</th>
<th>Percentage</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Cabernet Sauvignon</td>
<td>36</td>
<td>36%</td>
</tr>
<tr>
<td>2</td>
<td>Merlot</td>
<td>44</td>
<td>44%</td>
</tr>
<tr>
<td>3</td>
<td>Carménère</td>
<td>20</td>
<td>20%</td>
</tr>
<tr>
<td>Total</td>
<td></td>
<td>100</td>
<td>100</td>
</tr>
</tbody>
</table>

The information from each sample was obtained setting the parameters shown in Table I for the instrument. 10 measurements were done for each of the 100 sample obtaining in total 1000 profiles (chromatograms).

C. Data Pre-Processing

The chromatograms obtained from the electronic nose are curves of 12 sec. of duration with a sampling period of 0.02 sec., containing 600 points in total. Fig. 5 shows a typical profile corresponding to a Cabernet Sauvignon sample properly normalized.

The normalization process was done to normalize the
amplitude in the interval [-1, 1]. To this extent the maximum amplitude was used to normalize the signal according to the following relationship:

$$x_i' = \frac{x_i}{x_{\text{max}}}$$

where $x_{\text{max}}$ is the maximum amplitude of all profiles.

![Fig. 5 Typical normalized chromatogram for a Cabernet Sauvignon (600 points and 12 s of duration)](image)

### D. Methodology

In order to classify the profiles described in Section III B, the classification technique Radial Basis Functions Neural Networks (RBFNN) described in Section II B will be used. Because of the high data dimensionality, previous to the classification it was necessary to perform a feature extraction procedure of the original data using the Principal Component Analysis (PCA) technique described in Section II A.

The total database of 1000 profiles (360 Cabernet Sauvignon or Class 1, 440 Merlot or Class 2 and 200 Carménère or Class 3) was divided in two sets; one for training-validation (containing the 90% of the samples) and other for Test (containing the 10% of the samples). The sample distribution is the following:

**Training-Validation Set:** 900 profiles corresponding to 90 wine samples, 330 profiles Cabernet Sauvignon (33 samples), 390 profiles Merlot (39 samples), and 180 profiles Carménère (18 samples).

**Test Set:** 100 profiles corresponding to 10 wine samples, 30 profiles Cabernet Sauvignon (3 samples), 50 profiles Merlot (5 samples), and 20 profiles Carménère (2 samples).

The samples for each set were selected randomly and based on the proportion of the samples of different kind contained in the original database.

As a measure of the behavior and to obtain the optimal values of the parameters for each method, Cross-Validation was used [8, 10, 11]. The database was divided in $n$ sets, using $n-1$ for training and the reminder for validation. The process is repeated $n$ times so that all $n$ sets are used once for validation.

In the training-validation it will be used cross-validation with the aim to measure the behavior and to tune the optimal parameters for each classification feature extraction method. Then each classifier will be evaluated with the Test set, using the whole training-validation set and the optimal parameters determined by cross validation. It is important to notice that the Test Set is never used in the training stage and therefore will be completely unknown go the classifier and is a good performance measure of each method.

Since there is 10 profiles for each wine sample, the size of cross validation sets will be 10 and then the training-validation base will be divided in 90 sub-sets of 10 elements, each one representing one wine sample. Thus, for each method the training is done using 890 profiles and one simulation for validation having 10 elements. The process is repeated 90 times so that each subset of 10 elements is used once to validate the method. The measurement of the behavior will be the average and the standard deviation of the percentage of correct classification in validation.

Finally, once cross validation is done and the optimal parameters are found for each method, one simulation is done with the Test Set to evaluate the performance of each method when unknown samples are presented. The behavior will be measured again in terms of the average and the standard deviation of the percentage of correct classification in the test set.

### E. Feature Extraction using Principal Components Analysis (PCA)

The central idea of the principal components analysis (PCA) is to transform the input space of the variables $X$ onto a space $P'$ where the data is not correlated i.e. the variance of the data is maximum. This is achieved by computing the eigen-values and the eigen-vectors of the covariance matrix of the initial data and selecting those eigenvectors that have the largest eigen-values. These components represent the axes of the new transformed space. By projecting the initial data onto these axes the largest data variance is obtained.

The profiles can be seen as characteristic vectors belonging to $\mathbb{R}^{600}$ and the database as a matrix of $600 \times 1000$, where the 1000 columns correspond to each profile and the 600 rows to the points (that are going to be reduced).

Considering the training-validation set we have a matrix of $600 \times 900$ (900 profiles (columns) of 600 points (rows)). Then the covariance matrix of the training-validation set is

$$\Sigma_X = X^*X^T$$

with $X$ the training-validation matrix and $\Sigma_X$ the covariance matrix of $X$ of $600 \times 600$. Then computing the eigen-values and the eigenvectors of $X$ and selecting the eigen-vectors with the largest eigen-values the principal components transformation matrix will be determined. One way of choosing the eigen-values (and the eigenvectors associated) is considering the contribution to the global variance [8, 12] of
each eigen-value, \( \gamma_i \), as:

\[
\gamma_i = \frac{1}{N} \sum_{j=1}^{\infty} \lambda_j
\]

being \( N = 600 \) the total number of eigen-values of the covariance matrix \( X \).

\( \gamma_i \) associates to each eigen-value (and each eigen-vector or principal component) a factor of relative importance considering its contribution to the total variance.

When computing the eigen-values of the covariance matrix \( X \), these are ordered in ascending order \([11,19]\), thus the last components are those contributing the most to the information (in terms of the covariance) whereas the first can be considered as noise and therefore disregarded. In Fig. 6 are plotted the last 25 eigen-values (of a total of 600) of the training-validation covariance matrix of \( 600 \times 600 \).

![Fig. 6 Detail of the last 25 eigen-values of the training-validation covariance matrix](image)

Fig. 6 shows only the last 25 eigen-values of the values training-validation covariance matrix and it is observed that these retain practically all the information in terms of the covariance. When computing the contribution of the last 20 eigen-values to the global covariance using (9), the contribution to the total information is 99.87% and the last 10 eigen-values contribute 99.46%. Therefore we will choose the matrix transformation composed by the 20 eigen-vectors associated to the last 20 eigen-values, generating a \( 600 \times 20 \) matrix (the 600 rows represent the initial characteristics or points and the 20 columns the eigen-vectors or new characteristics). Multiplying each original profile by the transformation matrix a low dimension profile is obtained (dimension 20) which will be used in the classification procedure.

**IV. RESULTS**

As explained in Section II B, in a RBFNN is necessary to define the centers of the neurons and the parameters \( \sigma \) known as spread, which define the selectivity of the neuron. For all simulations the neurons were located at each training pattern \([28]\), thus when cross validation is carried out the networks has 890 neurons corresponding to each profile. Recall that the NN has two layers; the first has radial basis activation functions and the second linear activation functions.

Simulations were carried out making cross validation with the training–validation set for different values of the selectivity \( \sigma \), and computing the performance. The same was done for the test set.

For this method 20 principal components containing the 99.86% of the total information of the training-validation data were considered. That is to say the data dimension is reduced from 600 to only 20 pints.

Different values of the selectivity were considered in the interval \([2^{-9}, 10]\). For higher values of the selectivity the results were poor in both validation and test sets. The results obtained are presented in Table III.

<table>
<thead>
<tr>
<th>Selectivity</th>
<th>% Correct Classification in validation</th>
<th>Standard Deviation</th>
<th>% Correct Classification in test</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>39.8</td>
<td>0.4913</td>
<td>30</td>
</tr>
<tr>
<td>1</td>
<td>36.6</td>
<td>0.4845</td>
<td>50</td>
</tr>
<tr>
<td>0.1</td>
<td>60.8</td>
<td>0.4402</td>
<td>52</td>
</tr>
<tr>
<td>0.02</td>
<td>35.3</td>
<td>0.3557</td>
<td>63</td>
</tr>
<tr>
<td>0.01</td>
<td>53.5</td>
<td>0.3846</td>
<td>67</td>
</tr>
<tr>
<td>0.0078125</td>
<td>61.3</td>
<td>0.3641</td>
<td>65</td>
</tr>
<tr>
<td>0.00390625</td>
<td>66.1</td>
<td>0.3853</td>
<td>76</td>
</tr>
<tr>
<td>0.00195313</td>
<td>71.4</td>
<td>0.3776</td>
<td>60</td>
</tr>
</tbody>
</table>

Observing Table III it is appreciated that classification results do not reach the 80% of correct classification in the best case.

The simulations were carried out using the same computer already mentioned in the previous section and using the software Matlab 6.0, the Neural Network Toolbox and the Signal Processing Toolbox.

The average processing time for each simulation are shown in Table IV as a function of the number of principal components chosen. The average is computed over three runs performed for each simulation.

<table>
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<td>0.3776</td>
<td>60</td>
</tr>
</tbody>
</table>
The results exposed above indicate the necessity of having a larger database with uniform distribution of the classes. Finally, it is important to point out that the results gotten in this study are auspicious and corroborate that in spite of the reduced dimension of the database it is indeed possible to classify Chilean wines according to the cepas using chromatograms coming from an electronic nose.

V. CONCLUSIONS

The classification of red Chilean wines of the type Cabernet Sauvignon, Merlot and Carmenère, from different vintages and different valleys, was successfully performed based on the gas chromatograms supplied by an electronic nose.

Principal Component Analysis was used as feature extraction and Radial Basis Function Neural Networks as classification technique. The best parameters for each method were obtained from the cross validation process with the training-validation set.

The RBFNN showed a discrete performance in the training-validation set with classification rates about 71% (for \( \sigma=0.00195 \)) and a 76% in the test set (for \( \sigma=0.00391 \)).

For future studies it is suggested to analyze other feature extraction techniques like wavelets and other classification techniques as Support Vector Machines (SVM) Currently we are working in incorporating more wine samples to the original database to complete soon 200 samples. The idea is to repeat this study with this new database these new techniques.

The results obtained in this study are promising and the first on Chilean wines using gas chromatograms supplied by an electronic nose. They provide the basis for future work on classification of Chilean wines. Other work developed by the authors on this subject can be found in [14, 15, 16].

REFERENCES