A Robust Reception of IEEE 802.15.4a IR-TH UWB in Dense Multipath and Gaussian Noise

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Abstract—IEEE 802.15.4a impulse radio-time hopping ultra wide band (IR-TH UWB) physical layer, due to small duty cycle and very short pulse widths is robust against multipath propagation. However, scattering and reflections with the large number of obstacles in indoor channel environments, give rise to dense multipath fading. It imposes serious problem to optimum Rake receiver architectures, for which very large number of fingers are needed. Presence of strong noise also affects the reception of fine pulses having extremely low power spectral density. A robust SRake receiver for IEEE 802.15.4a IR-TH UWB in dense multipath and additive white Gaussian noise (AWGN) is proposed to efficiently recover the weak signals with much reduced complexity. It adaptively increases the signal to noise (SNR) by decreasing noise through a recursive least square (RLS) algorithm. For simulation, dense multipath environment of IEEE 802.15.4a industrial non line of sight (NLOS) is employed. The power delay profile (PDP) and the cumulative distribution function (CDF) for the respective channel environment are found. Moreover, the error performance of the proposed architecture is evaluated in comparison with conventional SRake and AWGN correlation receivers. The simulation results indicate a substantial performance improvement with very less number of Rake fingers.

Keywords—Adaptive noise cancellation, dense multipath propagation, IEEE 802.15.4a, IR-TH UWB, industrial NLOS environment, SRake receiver

I. INTRODUCTION

A carrier less, baseband physical layer (PHY) of impulse radio-time hopping ultra wide band (IR-TH UWB) is approved as [1]. The allowable frequency range is classified into a sub GHz, low (3.1 to 4.8 GHz) and high (6.0 to 10.6 GHz) band plans. Both GHz bands are further divided into 15 operating channels, each identified by a distinct center frequency and bandwidth. The $M = 4$ symbols of IEEE 802.15.4a IR-TH UWB rely on $M$ burst position modulation-burst position modulation-burst position shift keying (BPM-BPSK) modulated biorthogonal signals. Independent time hopping (TH) codes of different data streams allow multiple access communication without catastrophic collisions. The small duty cycle and very short pulse widths reduce intersymbol interference (ISI) and the inherent discontinuity mitigates the effects of constant interventions. It has strong potential against multipath fading, but due to fine time resolution and increased bandwidth, the scatterers and reflectors in non line of sight (NLOS) indoor surroundings generate a plenty of resolvable multipath components (MPCs). The situation is typically severe in industrial NLOS environment, where the presence of large metallic enclosures causes severe small scale fading and a dense power delay profile (PDP). To exploit this multipath diversity, a very large number of Rake fingers are needed for coherent reception.

Uptill now, the performance evaluation of IEEE 802.15.4a IR-TH UWB in dense multipath channels was mostly targeted towards positioning and acquisition as in [2] and [3]. Reception and error performance was also focused either over AWGN [4] or sparse residential and office environments [5]-[7]. However, simulations in [8] were carried out in dense IEEE 802.15.4a industrial NLOS environment available as channel model 8 (CM8). In the presence of large excess delays, the first ray does not carry the largest amplitude and hence selective-Rake (SRake) utilizing the strongest MPCs was employed instead of all-Rake (ARake) and partial-Rake (PRake) receivers. The results indicated an obligation of hundreds of fingers, but no solution to solve this problem is yet proposed.

In this paper, the error performance of SRake reception in dense multipath propagated IEEE 802.15.4a industrial NLOS environment of CM8 is focused. The channel impulse response and the respective PDP is generated. Using different number of strongest MPCs, the signal to noise ratio (SNR) statistic of the channel is evaluated and the respective CDFs are obtained. The adaptive noise cancellation principle of [9] commonly applied on voice signals is introduced with conventional SRake reception of IR-TH UWB signals. The proposed adaptive SRake architecture overcomes the complexity indicated in [8]. It cancels the noise from weak UWB signals and improves the SNR through an adaptive recursive least square (RLS) algorithm. The error performance is evaluated, which shows a significant improvement as compared to conventional SRake and AWGN correlation receivers.

The rest of the paper is organized as follows. Multipath propagation in IR-UWB is discussed in Section II. Section III gives an overview of the system model with complete description of signal construction and dense industrial NLOS channel. Robust receiver architecture is specifically proposed in Section IV. Results along with simulation detail are presented in Section V. Section VI concludes the final remarks.

II. MULTIPATH PROPAGATION IN IR-UWB

Multipath propagation causes an accretion of several delayed, attenuated and distorted replicas of the transmitted signal at the receiver. Each $k^{th}$ MPC generated due to interaction with the surroundings is inherited with an amplitude $a_k$, phase $\psi_k$ and delay $\tau_k$. If the delay difference of two MPCs satisfies Eq.(1), they are said to be resolvable.

$$|\tau_b - \tau_c| \gg \frac{1}{B} \quad (b \neq c) \quad (1)$$

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All such $K$ resolvable MPCs collectively define the channel impulse response as

$$ h(t) = \sum_{k=0}^{K-1} a_k \xi_k(t) * \delta(t - \tau_k) $$

(2)

However, the above equation best suits for carrier modulated signals, in which complex baseband technique is used to express the channel impulse response and the reception involves the generation of in phase and quadrature signals [10]. Comparatively in carrier less baseband IR-UWB, using pulse based transmitter and receiver, the channel impulse response is represented as a real pass band system and the phase $\phi$ is not considered. Due to increased frequency, all the multipath propagation effects in UWB channels become frequency dependent which give rise to distortion $\xi_k$ in each $k^{th}$ path of the received signal. The channel response of Eq.(2) for narrow band systems is no more a Dirac delta function [11], and is represented as

$$ h(t) = \sum_{k=0}^{K-1} a_k \xi_k(t) * \delta(t - \tau_k) $$

(3)

where * denotes convolution.

Under the slow fading assumption of the frequency selective channel, the gain $a_k$ and the delay $\tau_k$ are taken constant over a symbol duration. In the case of AWGN, which is assumed as independent of fading amplitudes $a_k$ with $N_0$ (W/Hz) as single sided power spectral density, the instantaneous SNR per symbol of $k^{th}$ path having $E_s$ as symbol energy is given by

$$ \gamma_k = (a_k^2 E_s)/N_0 $$

(4) and the respective total received instantaneous SNR $\gamma$ would be $\gamma = \sum_{k=0}^{K-1} \gamma_k$

III. SYSTEM MODEL

Uncoded IEEE 802.15.4a IR-TH UWB is modulated as a two bit symbol using BPM-BPSK employing TH codes. It generates a set of $M = 4$ biorthogonal signals transmitted through dense multipath propagated IEEE 802.15.4a industrial NLOS CM8. The received signal contaminated by strong AWGN and interferences is recovered via proposed robust SRake receiver as shown in Fig. 1. It includes a dual input adaptive noise canceler (ANC), SRake combiner and a maximum likelihood (ML) detector followed by a demodulator.

A. Signal Construction

According to [1], data for coherent detection is modulated as a two bit symbol using BPM-BPSK. It produces a burst of duration $T_{burst}$ using $N_{cph}$ consecutive pulses with each pulse occupying a small chip interval of $T_c = 2$ ns. The burst can be present in any of the possible $N_{hop}$ positions identified by independent TH codes. The code represents a sequence $[c_0, c_1, \ldots, c_{N_{hop}}]$ of integers defining respective burst locations in a data stream.

The first data bit $d_{iBPM}^{q_e}$ encodes the position of the burst in either half of the symbol duration $T_{BPM}$, while the second data bit $d_{iBPSK}^{q_e}$ indicates its polarity. If $E_s$ is the symbol energy and $p_{tx}(t)$ is the transmitted first derivative Gaussian pulse, $s_{txn}^{q_e}(t)$ represents the $m^{th}$ biorthogonal transmitted signal of $q^{th}$ node using $c^{th}$ TH code as

$$ s_{txn}^{q_e}(t) = \sqrt{E_s} \sum_{j=-\infty}^{N_{cph}} (1 - 2d_{iBPSK}^{q_e}) \sum_{x=1}^{N_{cph}} p_{tx}(t - c_j T_{burst} - xT_c - d_{iBPM}^{q_e} T_{BPM}) $$

(5)

B. Dense Multipath Propagated Industrial NLOS Channel

On behalf of extensive measurement campaigns and simulations, IEEE 802.15.4a offers several channel environments available as channel models (CM1 to CM9). By incorporating path loss, large and small scale fading, they provide realistic channel conditions for design and analysis for both 3 to 10 and below 1 GHz frequency ranges.

The most dense multipath propagated environment is available as industrial NLOS channel model 8. The analysis is based on modified Saleh and Valenzuela (SV) model for indoor multipath propagation, which indicates that the grouping of objects in the surroundings leads to clustering of MPCs. Using $a_{kl}$ and $\tau_{kl}$ as the gain and delay of $k^{th}$ cluster and $T_l$ as the arrival time of $l^{th}$ cluster, the channel impulse response appears as

$$ h(t) = \sum_{l=1}^{L-1} \sum_{k=0}^{K-1} a_{kl} \delta(t - T_l - \tau_{kl}) $$

(6)

Over a small area complex Gaussian best accounts for their amplitude variations, with an equivalent complex baseband
Rayleigh distribution. However, in the presence of large excess delays prevailing in NLOS industrial, the conventional distribution is no more valid for large number of non-resolvable MPCs in each delay bin [12]. Alternatively, Nakagami distribution with probability density function (PDF) shown in Eq.(7) has been suggested for small scale fading with a Lognormally distributed Nakagami \( m \) factor. The respective distribution is written as

\[
\text{pdf}(z) = \frac{2}{\Gamma(m)} \left( \frac{m}{\Omega} \right)^{m} z^{2m-1} \exp \left( -\frac{m}{\Omega} z^2 \right) \quad (7)
\]

Where \( \Gamma(m) \) is the gamma function and \( \Omega \) is the mean square value of the amplitude.

In other environments, the PDP appears with Poisson distributed cluster and ray arrival times. In contrast, with a single cluster in industrial NLOS channel, PDP is expressed as

\[
E\{ | s_{kl} |^2 \} = (1 - \chi) \cdot \exp \left( -\frac{\tau_{ris}}{\gamma_{1}} \right) \cdot \frac{\Omega_1}{\gamma_{1} + \gamma_{ris} (1 - \chi)} \quad (8)
\]

Where \( \chi \) represents the attenuation of first path and \( \gamma_{ris} \) and \( \gamma_{1} \) respectively pertaining the rising and decaying time constants.

Apart from the statistics and complete detail of small scale fading available in [13], the phenomenon of diffraction and reflection like in all other channel environments are frequency dependent for which modified path loss functions are consid- ered.

### C. Receiver Architecture

We introduce an adaptive noise canceler (ANC) at the front end of SRake combiner. The received signal through CM8 in the presence of AWGN appears at the primary input, while the correlated samples of the primary noise are applied at the other reference input. The ANC adaptively reduces the noise content and feeds the signal to four independent Rake units of the SRake combiner. Each \( m^{th} \) Rake unit relates to one of biorthogonal transmitted signals. In addition to weighting and delay coefficients, the matching template also rely on the impulse response of CM8. The Rake output is the decision metric on behalf of which the detector and demodulator provide the estimated symbol.

### IV. AN ADAPTIVE SRAKE RECEIVER

All the sections of the proposed receiver architecture with their respective inputs and outputs are mentioned in Fig. 2 as follows

#### A. RLS Adaptive Noise Canceler

For \( m^{th} \) transmitted signal, the respective mutually and statistically independent and identically distributed (\( \text{iid} \)) additive white Gaussian noise (AWGN) random variable has zero mean and variance given by

\[
\sigma^2_m = \frac{N_0}{2}, \quad m = 1, \ldots, M
\]

While neglecting the antenna effects and assuming \( h(t) \) as the impulse response of CM8, the corresponding received signal at the primary input of ANC is represented as \( s_{txm}(t) \). If \( * \) indicates the convolution operation and \( n_{pm}(t) \) as the primary noise added into the \( m^{th} \) transmitted signal, \( s_{txm}^{qc}(t) \) is given by

\[
s_{txm}^{qc}(t) = s_{txm}^{qc}(t) * h(t) + n_{pm}(t) \quad (10)
\]

Using \( i \) as time index, the above equation is written as

\[
s_{txm}^{qc}(i) = s_{txm}^{qc}(i) * h(i) + n_{pm}(i) \quad (11)
\]

where \( s_{txm}^{qc}(i) * h(i) \) designates our desired response \( d_{m}(i) \). The noise \( n_{pm}(i) \), a correlated version of primary noise appears at the reference input as the first tap input \( u_{pm}(i) \). After being adaptively filtered through \( M_{w} \) order tap weight vector as \( n_{fm}(t) \), it is subtracted from the primary input to produce an error signal \( e_{m}(i) \) at the output of an ANC.

\[
e_{m}(i) = s_{txm}^{qc}(i) - n_{fm}(i) \quad (12)
\]

The noise canceler actually adapts its impulse response through a tap weight vector. It minimizes the squared error via RLS algorithm mentioned in [14]. The filtered noise \( n_{fm}(i) \) is adjusted such that the noise power present in the primary input is reduced keeping the signal power unchanged. Thus, for the length of the observed data \( y_{i} \), equivalent to symbol duration, our objective function \( \varepsilon_{m}(y) \) is given by

\[
\varepsilon_{m}(y) = \sum_{i=1}^{y} \beta_{m}(y, i) \cdot | e_{m}(i) |^2 \quad (13)
\]

To minimize the objective function, the algorithm on the basis of initial known conditions and feed back samples recursively...
updates the old estimates of tap weight vector \( \mathbf{w}_m(y) \).

During the observation interval \( 1 \leq i \leq y \) equivalent to symbol duration, the forgetting factor \( 0 \leq \beta_m(y, i) \leq 1 \) of Eq.(14) is introduced to exponentially ignore the effect of past data.

\[
\beta_m(y, i) = \alpha_m^{y-i}
\]  

where \( \alpha_m \) is a positive constant close to, or equal to 1. The tap weight vector modifies the error signal according to

\[
e_m(i) = s_{\text{rxm}}^c(i) - \mathbf{w}_m^H(y) \mathbf{n}_{\text{rem}}(i)
\]

where \( s_{\text{rxm}}^c(i) \) indicates the time indexed sampled values of the received signal and \( \mathbf{w}_m^H(y) \) at \( (t = y) \) represents the conjugate transpose of \( \mathbf{w}_m(y) \).

Both the tap weight vector \( \mathbf{w}_m(y) \) and the time indexed reference noise vector \( \mathbf{n}_{\text{rem}}(i) \) are expressed as

\[
\mathbf{w}_m(y) = [w_{m0}(y), w_{m1}(y), \ldots, w_{m(M_w-1)}(y)]^T
\]

\[
\mathbf{n}_{\text{rem}}(i) = [n_{\text{rm}}(i), n_{\text{rm}}(i-1), \ldots, n_{\text{rm}}(i-M_w+1)]^T
\]

The optimal value of the tap weight vector, at which our objective function acquires the minimum, is represented as \( \hat{\mathbf{w}}_m(y) \). According to [14], it is the product of the inverse of \( \Phi_m(y) \) and \( \theta_m(y) \) written as

\[
\hat{\mathbf{w}}_m(y) = \Phi_m^{-1}(y)\theta_m(y)
\]

where \( \Phi_m^{-1}(y) \) is the \( M_w \) by \( M_w \) time averaged correlation matrix of tap inputs given by

\[
\Phi_m^{-1}(y) = \sum_{i=1}^{y} \alpha_m^{y-i} \mathbf{u}_m(i)\mathbf{u}_m^H(i)
\]

and \( \theta_m(y) \) of \( m^{th} \) signal is the \( M_w \) by 1 time averaged cross correlation vector between the tap inputs and the complex conjugation of desired response \( d_m(i) \) indicated as

\[
\theta_m(y) = \sum_{i=1}^{y} \alpha_m^{y-i} \mathbf{u}_m(i)d_m^*(i)
\]

The received signal after being adaptively filtered at the output of ANC is represented as \( r_s(i) \). It is applied to the four Rake units, where the resultant increased SNR is effectively utilized to reduce the required number of fingers.

### B. SRake Combiner

The branch statistic of SRake combiner was found by generating an impulse response of CMS using Matlab function uwb-sv-model-ct-15-4a.m provided in [15]. The function provides 100 realizations of channel impulse response \( h(t) \) at each sampling interval \( T_s \). Average of \( h(t) \) at each sampling interval gives the channel vector \( \mathbf{h} \) with the corresponding time index vector \( \mathbf{t} \) available in Eq.(21) and Eq.(22) as

\[
\mathbf{h} = [h_0(0), h_1(T_s), \ldots, h_{K-1}(K-1)T_s]^T
\]

\[
\mathbf{t} = [0, T_s, \ldots, (K-1)T_s]^T
\]

Representing the strength of all the received \( K \) MPCs, \( \mathbf{h} \) was then sorted for \( K_s \) strongest MPCs in \( \mathbf{h}_s \) with time index \( \tau_s \) as

\[
\mathbf{h}_s = \left[ h_0(\tau_0), h_1(\tau_1), \ldots, h_{(K_s-1)}(K_s-1)\right]^T
\]

\[
\tau_s = [\tau_0, \tau_1, \ldots, (K_s-1)]^T
\]

The above two vectors respectively represent the branch weighting coefficients \( \mathbf{w}_s \) and delay elements of SRake combiner.

Each \( m^{th} \) Rake unit, uses a set of \( K_s \) fingers (branches) enclosed within dashed boxes of Fig. 2.

The locally generated matching template \( \nu_m^c(t) \) after neglecting the antenna effects is selected for one complete symbol duration. For \( m^{th} \) signal using \( c^{th} \) TH code assigned to \( q^{th} \) node, it is therefore chosen as

\[
\nu_m^c(t) = s_{\text{txm}}^c(t) * h(t)
\]

Each branch correlates the received signal with the matching template delayed by \( \tau_s \) and weighted by \( w_s \). The sum of all the branch outputs corresponding to a maximal ratio combiner (MRC) is treated as a decision metric \( \rho_m \) as follows

\[
\rho_m = \sum_{s=0}^{K_s-1} w_s.C_m(\tau_s(t), \nu_m^c(t - \tau_s))
\]

where \( C_m(a,b) \) represents the correlation between \( a \) and \( b \) entities.

These \( \rho_m \) values for the four biorthogonal signals fed into a detector and a demodulator for final estimation of the transmitted symbol.

### C. Detector

Assuming perfectly synchronized transmitter and receiver, the signal detection was analyzed and simulated as a single data stream using \( c^{th} \) TH code. The estimated signal \( s_{\text{txm}}^c(t) \) is based on maximum likelihood (ML) detection where the value of the largest weighted correlation sum decides one of \( M \) signals as

\[
s_{\text{txm}}^c(t) = \arg \max_{m} \rho_m
\]

Finally the demodulator provides the corresponding symbol.

### V. SIMULATION AND RESULTS

Simulations were carried out in IEEE 802.15.4a industrial NLOS environment of CMS at a center frequency \( f_c = 7.987 \) GHz of channel 11 of high band plan. The large center frequency was selected to enhance immunity against dense multipath propagation. With a sampling frequency of \( f_s = 50 \) GHz, the channel impulse response was generated based on [15]. The average PDP of Fig. 3 produced on behalf of it, clearly shows the dense accumulation of MPCs, with the first arriving component not indicating the largest amount of energy.

Channel realizations of CMS were generated 1000 times and histograms using 20 and 100 strongest MPCs were obtained. It gives the discrete approximation of the PDFs of the instantaneous received SNR of selected MPCs from which respective
Fig. 3. Power Delay Profile of CM8

CDFs were obtained. Fig. 4 indicates that in IEEE 802.15.4a industrial NLOS CM8 following Nakagami distribution for small scale fading, an approximate gain of only 5 dBs is achieved when selected strongest MPCs are increased from 20 to 100.

Fig. 4. The CDF of received instantaneous SNR obtained from 20 and 100 strongest MPCs of 1000 channel realizations of CM8. The average transmitted SNR=0 dB

To simulate the performance of ANC, 1000 random samples of primary noise $n_{rm}(i)$ were generated and passed through a 32 order low pass filter (LPF) to obtain the respective correlated reference noise samples of $r_{rm}(i)$. A correlation strength $\rho_{rm}(i)$ ranging from -0.08 to +0.07 was obtained.

For the simulation of RLS algorithm, Identity matrix $I$ was selected as $\Phi_m(y)$ of Eq. (19). The tap weight vector $w_m(y)$ was initialized using all zeros vector with the exponential weighting factor $\alpha_m=1$. To keep the recursions in progress and for the initial setting of the correlation matrix, $\Phi_m(y)$ was multiplied with a small positive value $\delta_m=0.1$.

Using $M_w = 32$ as the order of tap weight vector, the obtained correlation strength between the desired response $d_m(i)$ and the output $r_d(i)$ of ANC varying between +0.65 to +0.9 due to $\phi_m(i)$ is depicted in Fig. 5. It can be seen that even for $\phi_m(i)$ of less than 0.01, ANC still provides a correlation strength greater than 0.6 between the desired response and the output of ANC.

Although, in practical scenario the correlated noise samples for the reference signal can be obtained using a side lobe of an antenna array with the primary input being received from far field at the main lobe.

The adopted values of $f_c$ and $N_{chpb}$ for $R_b$ the bit rate, $T_c$ the chip duration and $N_c$ the number of chips per symbol of channel 11 of [1] are mentioned in Table(I).

<table>
<thead>
<tr>
<th>$f_c$ (GHz)</th>
<th>$R_b$ (Mb/s)</th>
<th>$T_c$ (ns)</th>
<th>$N_{chpb}$</th>
<th>$N_c$</th>
<th>$N_{hop}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>7.987</td>
<td>0.85</td>
<td>2</td>
<td>16</td>
<td>256</td>
<td>8</td>
</tr>
</tbody>
</table>

Using the above parameters, the error performance of BPM-BPSK modulated IR-TH UWB biorthogonal signals was found in IEEE 802.15.4a industrial NLOS environment of CM8 in the presence of AWGN. Both the conventional SRake and robust SRake receivers employ 20 fingers in each Rake unit. An appreciable performance improvement is observed with a proposed robust SRake which provides a gain of approximately 33 dBs and 5 dBs respectively with the conventional SRake and AWGN correlation receivers as shown in Fig. 6. It is therefore suggested, that instead of using hundreds of Rake fingers, an addition of an ANC drastically improves the error performance of conventional SRake receiver in dense multipath propagated environment.

VI. CONCLUSION

The generated power delay profile of IEEE 802.15.4a industrial NLOS environment of CM8 exhibits dense multipath
fading, with the first ray not carrying the highest magnitude. The number of resolvable multipath components increases with the bandwidth, for which plenty of diversity paths are needed to obtain an appreciable increase in instantaneous SNR. By including an adaptive noise canceler, the proposed robust SRake architecture with very less number of fingers, effectively recovered the weak BPM-BPSK modulated IR-TH UWB biorthogonal signals in CM8. The respective error performance depicts a significant improvement as compared to both the conventional SRake and AWGN receivers.

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