Induction of Expressive Rules using the Binary Coding Method

Seyed R Mousavi

Abstract—In most rule-induction algorithms, the only operator used against nominal attributes is the equality operator =. In this paper, we first propose the use of the inequality operator, ≠, in addition to the equality operator, to increase the expressiveness of induced rules. Then, we present a new method, Binary Coding, which can be used along with an arbitrary rule-induction algorithm to make use of the inequality operator without any need to change the algorithm. Experimental results suggest that the Binary Coding method is promising enough for further investigation, especially in cases where the minimum number of rules is desirable.

Keywords—Data mining, Inequality operator, Number of rules, Rule-induction.

I. INTRODUCTION

In general, a rule induction algorithm operates on a given dataset and generates a model based on a set of rules. One of the main types of attributes in such datasets is the nominal type. The value of a nominal attribute is usually a value in a predefined and finite set of discrete values. For example, in an application, we may define Color as an attribute which can only be Red, Green, or Blue. Other examples of nominal attributes include the Family, Product-type, Steel, and Formability in the Annealing dataset, all the attributes in the Car Evaluation, and all the attributes in the Vote datasets, which can all be found in the UCI Data Repository [1], at http://www.ics.uci.edu/~mlearn/MLRepository.html.

For the purpose of this paper, we introduce two types of nominal attributes. By a binary nominal attribute, or for short a binary attribute, we mean a nominal attribute which only has two possible values; e.g. Gender, which can only be Male or Female. On the other hand, by a multi-value nominal attribute, or for short a multi-value attribute, we mean an attribute which has more than two possible values. For example, if Color can be Red, Green, or Blue, then it will be a multi-value attribute.

Most well-known rule-induction algorithms only use the equality operator, =, against multi-value attributes [2]-[5]. In this paper, we propose the use of the inequality operator, ≠, in addition to the equality operator, against multi-value attributes. We first explain how this would increase the expressiveness of the induced rules, thereby giving the potential for reducing the number of rules. Obviously, a possible way to include the inequality operator in a rule-induction algorithm is to modify the algorithm. This would be desirable with respect to flexibility, i.e. the way the inequality operator is handled within the algorithm is completely under control and can be customized for that specific algorithm. However, in most cases, it would not be possible, or at least not desirable, to do so; e.g. the user of the algorithm might not be a computer programmer, or there might not be access to the code of the algorithm. To overcome this issue, in this paper we also present a new method called Binary Coding, which allows for a rule-induction algorithm to make use of the inequality operator, without any need to modify the algorithm.

The rest of the paper is organized as follows. Section II describes how the use of the inequality operator against multi-value attributes allows for more expressive rules. In Section III, we outline possible approaches to make use of the inequality operator. We describe the Binary Coding method in Section IV. Experimental Results are presented in Section V. Section VI summarizes the paper.

II. MORE EXPRESSIVENESS BY INEQUALITY OPERATOR

Let α be a multi-value attribute with n possible values of v₁, v₂, ..., vₙ. The reason why the use of the inequality operator allows for higher expressiveness of rules is that (i) a single test α ≠ vᵢ, 1 ≤ i ≤ n, is equivalent to the disjunction of n-1 test of α = vᵢ, where j ≠ i and 1 ≤ j ≤ n, i.e.:

\[ (α ≠ vᵢ) = \bigvee_{j \neq i} (α = vⱼ) \]

and (ii) the condition part of rules are normally conjunctions, as opposed to disjunctions, of tests; i.e. disjunctions must be represented by several rules. To clarify this, consider the

<table>
<thead>
<tr>
<th>Theory</th>
<th>Project</th>
<th>Gender</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>High</td>
<td>Good</td>
<td>F</td>
<td>Pass</td>
</tr>
<tr>
<td>Low</td>
<td>Good</td>
<td>M</td>
<td>Fail</td>
</tr>
<tr>
<td>High</td>
<td>Bad</td>
<td>M</td>
<td>Fail</td>
</tr>
<tr>
<td>Low</td>
<td>Bad</td>
<td>F</td>
<td>Fail</td>
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<tr>
<td>High</td>
<td>Good</td>
<td>M</td>
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</tr>
<tr>
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<td>Good</td>
<td>M</td>
<td>Pass</td>
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<tr>
<td>High</td>
<td>Bad</td>
<td>F</td>
<td>Fail</td>
</tr>
<tr>
<td>Med</td>
<td>Bad</td>
<td>F</td>
<td>Fail</td>
</tr>
</tbody>
</table>

TABLE I
A SAMPLE DATASET

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dataset shown in Table I.

In this dataset, there are three attributes: Theory, Project, and Gender. Project and Gender are both binary because each of them has only two possible values: Good and Bad for Project, and Female (F) and Male (M) for Gender. On the other hand, Theory is a multi-value attribute because it has three possible values: High, Medium (Med.), and Low.

The following ruleset, $R$, has been derived by applying ID3 [6] to this dataset:

1. IF Project=Good AND Theory=High $\rightarrow$ Pass
2. IF Project=Good AND Theory=Mid $\rightarrow$ Pass
3. IF Project=Good AND Theory=Low $\rightarrow$ Fail
4. IF Project=Bad $\rightarrow$ Fail

Using the $\neq$ operator, it is possible to obtain the following ruleset, say $R'$, which has fewer rules (3 instead of 4) and fewer tests (5 instead of 7):

1. IF Project=Good AND Theory $\neq$ Low $\rightarrow$ Pass
2. IF Project=Good AND Theory $\neq$ Mid $\rightarrow$ Pass
3. IF Project=Bad $\rightarrow$ Fail

It is easy to see that $R'$ is equivalent to $R$ (rules 1 and 2 in $R$ are reduced to rule 1 in $R'$). In other words the use of the $\neq$ operator in the first rule of $R'$ has increased its expressive power such that it is now equivalent to the first two rules in the ruleset $R$.

In the general case, let $a_1, a_2, \ldots, a_n$ be $n$ distinct multi-value attributes with, respectively, $m_1, m_2, \ldots, m_n$ nominal values. If a rule consists of $k_i$ tests with $\neq$ against attribute $a_i$, $k_i$ tests with $\neq$ against attribute $a_{i+1}$, ..., and $k_n$ tests with $\neq$ against attribute $a_n$, then it will be equivalent to $\prod_{i=1}^{n} (m_i - k_i)$ rules in which only $=$ has been used against the attributes $a_1, a_2, \ldots, a_n$.

In the case of the first rule in $R'$, for instance, we have $n=1$, $m_1=3$, and $k_1=1$. So the rule is equivalent to 2 rules with $=$ operator, i.e. the first two rules in $R$.

III. HOW TO INDUCE RULES WITH INEQUALITY OPERATOR

Let us use $R''$ to denote a ruleset in which the inequality operator, $\neq$, is allowed, and keep $R$ to denote a ruleset with the ordinary syntax. In general, a rule-induction algorithm, $A$, operates on a given dataset $D$ and generates a ruleset $R$ as in Fig. 1.

In order to obtain a ruleset $R''$, there are several possibilities, which include:

--Extend the algorithm $A$ to $A'$ such that $A'$ considers $\neq$ as a possible operator, in addition to $=$, against multi-value attributes (Fig. 2).

Fig. 2. Algorithm $A'$ is an Extension of Algorithm $A$

--Devis a transformer algorithm that converts $R$ to $R''$, independently from the underlying algorithm $A$ (Fig. 3). In other words, the original algorithm $A$ is used as usual to generate $R$, and then a transformer algorithm converts $R$ to $R''$, irrespective from $A$.

Fig. 3. Use a Transformer Algorithm to Convert $R$ to $R''$.

The advantage of the first approach is that the way the inequality operator is used in an algorithm is entirely under the control and can be customized for that algorithm to achieve more desirable results. C4.5, for instance, is a sort of algorithms which has followed this approach [7]. Although it does not explicitly generate rules with the inequality operator, it uses the $\neq$ to operator, when run with $-$ switch, which is implicitly equivalent to using the inequality operator. However, the disadvantage with the first approach is that it has to be done for each individual algorithm separately.

The second approach, on the other hand, works independently from the underlying algorithm. In other words, if a transformer algorithm is devised to convert a ruleset $R$ to an equivalent ruleset $R''$, then it will not be restricted to specific algorithms. However, no such algorithm has been proposed yet.

The method of Binary Coding, which is described in detail in the next section, has the advantage of the second approach, i.e. it is a generic method independent from the underlying algorithm. Moreover it is simple.

IV. THE METHOD OF BINARY CODING

The method of Binary Coding (Fig. 4) adds two modules to a rule-induction system: (1) a pre processor called Binary Encoder and (2) a post processor called Binary Decoder. These two modules are co-related but entirely independent from the underlying rule-induction algorithm. Therefore, this
approach is a generic approach which may be applied to an arbitrary rule-induction algorithm.

![Diagram](image.png)

Fig. 4. The Binary Coding Method.

The Binary Encoder and the Binary Decoder are described below:

A. Binary Encoder

The Binary Encoder is used to encode the dataset $D$ into another dataset $D_b$ in the following way. Let $a$ be a multi-value attribute with $k$ possible values $v_1, ..., v_k$. Then in $D_b$, $a$ is replaced by $k$ binary attributes $a_{j1}, ..., a_{jk}$, such that for each sample $x$, the value of $a_j$ will be 1 if and only if the value of $a$ for $x$ in $D$ is $v_j$. Note that for each sample in $D_b$, at most, one of the attributes $a_{j1}, a_{j2}, ..., a_{jk}$ can be 1, because $a$ in $D$ cannot have more than one value for each sample. If the value of $a$ is missing, then the value of every $a_j$ will also be considered as missing. We will call $D_b$ a binary dataset because it is a dataset with no multi-value attribute.

![Algorithm](algorithm.png)

Algorithm Binary Encoder

$D_b \leftarrow D$

For each multi-value attribute $a$ in $D$ with $k$ possible values $v_1, v_2, ..., v_k$ do

Replace attribute $a$ in $D_b$ with $k$ binary attributes $a_{j1}, a_{j2}, ..., a_{jk}$.

For each sample $x$ do

If value of $a$ in $D$ is missing then

set the value of each $a_{ji}, \forall i, k \in D_b$, as missing

Else

Let the value of $a$ be $v_i$, $1 \leq i \leq k$

set the value of $a_{ji}$ in $D_b$, as 1

set the value of $a_{j \neq i}$ in $D_b$ as 0

End.

The Binary Encoder module can be represented by the following algorithm:

B. Binary Decoder

Let $a$ be a multi value attribute in $D$ with $k$ possible values $v_1, v_2, ..., v_k$ which has been replaced with $k$ binary attributes $a_{j1}, a_{j2}, ..., a_{jk}$ in $D_b$. As the rule-induction algorithm operates on $D_b$, as opposed to $D$ (Fig. 4), the resulting ruleset $R_b$ would be expressed in terms of attributes $a_{j1}, a_{j2}, ..., a_{jk}$, as opposed to attribute $a$. However, since the original dataset $D$ is based on attribute $a$, and not attributes $a_{j1}, a_{j2}, ..., a_{jk}$, it is desirable to convert each test based on $a_j$ to the equivalent test based on the original attribute $a$. This conversion is the duty of the Binary Decoder module.

Let $a=b$, where $b$ is either 0 or 1, be a test used in a rule in the ruleset $R$. This test evaluates to true if and only if:

- $b=1$ and the value of the original attribute $a$ is $v_j$, or
- $b=0$ and the value of the original attribute is anything other than $v_j$.

In other words, the test $a=b$ can be replaced with $a=v_j$ when $b=1$ and with $a \neq v_j$ when $b=0$.

![Algorithm](algorithm.png)

Algorithm Binary Decoder

$R' \leftarrow R_b$

For each multi-value attribute $a$ in $D$ with $k$ possible values $v_1, v_2, ..., v_k$ which correspond respectively to attributes $a_{j1}, a_{j2}, ..., a_{jk}$ in $D_b$ do

For each rule $r$ in $R'$ do

replace each test ($a=b$) in $r$ with ($a=v_j$)

replace each test ($a=\neq v_j$) in $r$ with ($a \neq v_j$)

End.

The Binary Decoder module can be represented by the following algorithm:

V. EXPERIMENTAL RESULTS

In order to test the Binary Coding method we applied it to the TDIDT(entropy), Prism (standard), and J-Rule algorithms, using the Inducer software [8], [9]. All of the datasets are selected from the UCI repository [1].

The results of the experiments are shown in Table II. The first column shows the underlying dataset. The second column indicates the total number of classes in the datasets. The third column includes the number of attributes (binary, multi-value, and continuous, respectively). The last three columns show the results for TDIDT, Prism, and J-Rule algorithms, respectively. The experiments are based on the 10-fold test [9]. For each dataset for each algorithm, there are two sets of figures: the figures at the top are the result without using Binary Coding, and the ones at the bottom are the results when it has been used. For each set of data, there are three values. The first value is the average number of rules, the second value (inside parentheses) is the average number of tests per rule, and the last value is the average correct percentage. The correct percentage is the ratio of the number of samples for which the resulting ruleset provides the right class to the total number of samples.

As indicated in Table II, the Binary Coding method has improved considerably the TDIDT output for most of the cases. For Prism and J-rule, the improvement in the number of rules is roughly within 10% for about 66% of the cases. Among the other 34%, considerable improvements can be seen for the Nursery (about 50%) and Car Evaluation datasets (about 40%). In most of the cases, the correct percentage has not been affected considerably. However, in majority of cases,

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It has slightly been improved by Binary Coding.

VI. CONCLUSION

In this paper, we firstly showed how the use of the inequality operator “≠”, in addition to the equality operator, could result in higher expressiveness of rules induced by rule-induction algorithms. We then introduced three possibilities to use the inequality operator. One of these possibilities is the Binary Coding method, which simply adds to a rule-induction system two extra layers of pre-processing and post-processing without actual changing the underlying rule-induction algorithm itself. This brings the remarkable advantage that we do not need to change the underlying rule-induction algorithm in order to make use of the inequality operator. In other words, the method of Binary Coding operates independently from the underlying rule-induction algorithm.

One of the main possibilities for future work could be to investigate the characteristics of datasets on which the Binary Coding method performs well; in other words to find the class of datasets where Binary Coding could be advantageous. Another possible work could be to extend the use of the inequality operator to continuous attributes in order to increase the likelihood of achieving fewer and more expressive rules.

REFERENCES


