A Proposed Technique for Software Development Risks Identification by using FTA Model

Hatem A. Khater, A. Bait Mohamed, and Sara M. Kamel

Abstract—Software Development Risks Identification (SDRI), using Fault Tree Analysis (FTA), is a proposed technique to identify not only the risk factors but also the causes of the appearance of the risk factors in software development life cycle. The method is based on analyzing the probable causes of software development failures before they become problems and adversely affect a project. It uses Fault tree analysis (FTA) to determine the probability of a particular system level failures that are defined by A Taxonomy for Sources of Software Development Risk to deduce failure analysis in which an undesired state of a system by using Boolean logic to combine a series of lower-level events. The major purpose of this paper is to use the probabilistic calculations of Fault Tree Analysis approach to determine all possible causes that lead to software development risk occurrence.

Keywords—Software Development Risks Identification (SDRI), Fault Tree Analysis (FTA), Taxonomy for Software Development Risks (TSDR), Probabilistic Risk Assessment (PRA).

I. INTRODUCTION

In software development, the possibility of reward is high, but so is the potential for disaster. The need for software risk management is illustrated in Gilb’s risk principle. "If you don’t actively attack the risks, they will actively attack you" [Gilb-88] [1]. Risk management techniques, when correctly applied, can help ensure the successful outcome of software projects. Risks are potential issues that, if not identified and managed, could unexpectedly surface and cause substantial trouble when least expected. There are many philosophies and approaches for managing risks, including those discussed by Boehm (1989) and Charette (1989). The first step in risk management is to identify and prioritize the risk areas relevant to a project. Each project has different risks due to the unique characteristics that differ from project to project [2]. There are several Risk Management models and the most used one is SEI (Software Engineering institute) Risk Management paradigm that consists of five sequential and iterative steps: Identification, Analysis, Planning, Tracking and Control. In parallel, two common activities are performed: Documentation and Communication. The SEI Risk Management paradigm is depicted in Fig. 1 – (Risk Management Model) [3]. The paradigm illustrates a set of functions that are identified as continuous activities through the life cycle of a project. The method was originally developed as a project management method and the element of risk management was later added to the equation.

<table>
<thead>
<tr>
<th>Table I</th>
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<tbody>
<tr>
<td><strong>Risk Management Model Process</strong></td>
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<tr>
<td><strong>Function</strong></td>
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<tr>
<td>Identification</td>
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<tr>
<td>Analysis</td>
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<td>Planning</td>
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<td>Tracking</td>
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<tr>
<td>Control</td>
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<tr>
<td>Documentation &amp; Communication</td>
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</table>

The remainder of this paper focuses on risk identification and is based on the simple premise that without effective and repeatable risk identification methods, truly effective risk management is impossible; you can’t manage what you don’t know about. In keeping with this approach, the described
identification method also begins to address the communication issue central to risk management. In this paper basic concepts of Software Risk Management is introduced; In Section II we will introduce the Software Risk Identification and the Taxonomy for Software Development Risks (TSDS) that are presented by SEI; then in Section III a short introduction of Probabilistic Risk Assessment (PRA); then in Section IV the Fault Tree Analysis model is introduced; finally in Section V applying Fault tree analysis approach to identify all potential causes leading to software development risk occurrence.

II. RISK IDENTIFICATION

Risk Identification in projects means to determine potential risk elements by using a consistent and structured method; this is, probably, the most important step among those that compound the Risk Management activities, due to the fact that without a correct risks determination, it is not possible to develop and to implement in advance proper responses to the problems that could appear in the project [4]. The result of the risks identification is a list that contains the risks that have been identified and their related characteristics. Taxonomies are sorted classifications of elements according to their presumed relationship; they can be used as a very useful tool on different areas of the science and the industry where it is required to organize and to expedite the access to a wide set of related elements [3,5].The SEI risk identification method is based on the following assumptions:

1) Software development risks are generally known by the project’s technical staff but are poorly communicated.
2) A structured and repeatable method of risk identification is necessary for consistent risk management.
3) Effective risk identification must cover all key development and support areas of the project.
4) The risk identification process must create and sustain a non-judgmental and non-attributive risk elicitation environment so that tentative or controversial views are heard.
5) No overall judgment can be made about the success or failure of a project based solely on the number or nature of risks uncovered.

The SEI taxonomy of software development maps the characteristics of software development and hence of software development risks.

A. The Software Development Risk Taxonomy

Central to the risk identification method is the software development taxonomy. The taxonomy provides a framework for organizing and studying the breadth of software development issues. Hence, it serves as the basis for eliciting and organizing the full breadth of software development risks both technical and non-technical. The taxonomy also provides a consistent framework for the development of other risk management methods and activities. The software taxonomy is organized into three major classes.

- Product Engineering: The technical aspects of the work to be accomplished.
- Development Environment: The methods, procedures, and tools used to produce the product.
- Program Constraints: The contractual, organizational, and operational factors within which the software is developed but which are generally outside of the direct control of the local management.

These taxonomic classes are further divided into elements and each element is characterized by its attributes [6].

III. PROBABILISTIC RISK ASSESSMENT (PRA)

PRA is a systematic and comprehensive methodology to evaluate risks associated with every life-cycle aspect of a complex engineered technological entity from concept definition, through design, construction and operation, and up to removal from service [11]. Fault Tree Analysis (FTA) is one of the most important logic and probabilistic techniques used in PRA and system reliability assessment today. Over the past two decades, probabilistic risk assessment and its underlying techniques, including FTA, has become a useful and respected methodology for safety assessment. Because of its logical and systematic approach, PRA and FTA have been proven capable of uncovering design and operational weaknesses that escaped even some of the best deterministic safety. A foremost strength of PRA and its underlying analysis techniques, including FTA, is that it is a decision support tool. In safety applications, this methodology helps managers and engineers find design and operational weaknesses in complex systems and then help them systematically and efficiently uncover and prioritize safety improvements [10].

IV. FTA MODEL

Fault Tree Analysis (FTA) is one of the oldest, most diffused techniques in industrial applications, for the dependability analysis of critical systems [7]. The FTA is a deductive method: beginning with an undesired event (also called the top event) the FTA is used to find the causes for this top event. When determining the causes, a fault tree is constructed from top to bottom. For its construction several symbols are used that indicate the relation between different events. The main symbols are presented in Table II [8]. One of the main restrictive assumptions in FTA is that basic events must be assumed to be statistically independent, and their interaction is described by means of Boolean OR/AND gates, so that only the combination of events is relevant, and not their sequence. We refer to this model as Static Fault Tree (SFT) [9]. The gates show the relationships of events needed for the occurrence of a “higher” event. The “higher” event is the output of the gate; the “lower” events are the “inputs” to the gate. The gate symbol denotes the type of relationship of the input events required for the output event [11].
OR Gate denotes the situation in which an output event occurs if any one or more of the input events occur.

AND Gate denotes the situation in which an output event occurs only when all the input events occur.

RECTANGLE denotes an event that results from the combination of fault events through the logic gate.

CIRCLE denotes a basic fault event.

The Fault Tree Analysis is used for reliability and safety security analyses. The proceeding is very similar to the Reliability Block Diagram RBD. The aim is to determine possible combinations of causes which can lead to certain undesirable events (event), the so called top level events. The job of a FTA is as follows:
- The generation of a graphic / logical tree structure to the understanding of the connections.
- Identification of possible failure causes and their combinations.
- Calculation of the probability of the undesirable event.
- Comparison of variations.

A. Reliability & Failure Probability Relationships
- \( S \) = Successes
- \( F \) = Failures
- Reliability :
\[
R = \frac{S}{S+F}
\]
- Failure Probability:
\[
P = \frac{F}{S+F}
\]
\[
R + PF = \frac{S}{S+F} + \frac{F}{S+F}
\]

B. Reliability (R) & Failure Probability (PF) through Gates
Gates are the logic symbols that interconnect contributory events and conditions in a fault tree diagram. The AND and OR gates, as well as Voting OR gates in which the output event occurs if a certain number of the input events occur, are the most basic types of gates in classical fault tree analysis.
- **AND Gate**:
Both of two, independent elements must fail to produce system failure.

![Fig. 2 AND Gate](image)

\[
R_T = R_A + R_B - R_A R_B
\]
\[
P_F = 1 - R_T
\]
\[
P_F = 1 - (R_A + R_B - R_A R_B)
\]
\[
P_F = 1 - [(1 - P_A) + (1 - P_B) - (1 - P_A) (1 - P_B)]
\]
\[
P_F = P_A P_B
\]

(1)

- **OR Gate**:
Consider a system with two components: A and B. The system fails if both A and B fail [13].

![Fig. 3 OR Gate](image)

\[
R_T = R_A R_B
\]
\[
P_F = 1 - R_T
\]
\[
P_F = 1 - (R_A R_B)
\]
\[
P_F = 1 - [(1 - P_A) (1 - P_B)]
\]
\[
P_F = P_A + P_B - P_A P_B
\]

(2)
The next figure shows a simple Fault Tree

![Fault Tree Diagram]

The probability of top event failure is calculated as shown:

\[ P_{\text{top}} = P_A \cdot [P_B + P_C - P_B P_C] \]

V. PROPOSED MODEL

The proposed model that described in this paper is based upon the SEI taxonomy of software development risks. The taxonomy provides a framework for organizing and studying the breadth of software development issues and hence provides a structure for surfacing and organizing software development risks. Using Fault Tree Analysis and Probabilistic Risk Assessment is able to find the causes to undesirable events and to evaluate the risk quantitatively; the fault tree is constructed by first identifying the top fault event, which, in this case, is a Programmatic Risks class. The secondary events that are contributed directly to the top fault are the elements that are listed under Programmatic Risks class. These secondary events are further broken down to determine the root causes. We consider that the attributes is the last level of this tree which called the minimal cutsets of this fault tree (leaf events) that are contributed directly to the elements on the Taxonomy. Fig. 5 shows the completed fault tree for Programmatic Risks class. A minimal cutset is a smallest combination of component events which, if they all occur, will cause the top event to occur.

![Fault Tree Diagram]

Using equations (1) and (2), we can calculate the probability of Top event failure by the next equation:

\[ P_{CT} = P_{C1a} P_{C1b} P_{C1c} P_{C1d} \]
Therefore, the probability of risk of class C can be determined by next equation:
\[ P_C = P_{C1} + P_{C2} + P_{C3} - P_{C1} P_{C2} - P_{C1} P_{C3} - P_{C2} P_{C3} + P_{C1} P_{C2} P_{C3} \] (6)

The Table IV shows nominal values of basic events’ probabilities of occurrence. Then, using equations (3) to (6), the probabilities of intermediate events and at last probabilities of the Top Event should be determined. The Table V shows the results of result of the used model.

### TABLE IV
INITIAL DATA

<table>
<thead>
<tr>
<th>Event</th>
<th>Probability</th>
</tr>
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<tbody>
<tr>
<td>P_{C1a}</td>
<td>0.07</td>
</tr>
<tr>
<td>P_{C2a}</td>
<td>0.03</td>
</tr>
<tr>
<td>P_{C3a}</td>
<td>0.07</td>
</tr>
<tr>
<td>P_{C1b}</td>
<td>0.04</td>
</tr>
<tr>
<td>P_{C2b}</td>
<td>0.01</td>
</tr>
<tr>
<td>P_{C3b}</td>
<td>0.02</td>
</tr>
<tr>
<td>P_{C1c}</td>
<td>0.06</td>
</tr>
<tr>
<td>P_{C2c}</td>
<td>0.02</td>
</tr>
<tr>
<td>P_{C3c}</td>
<td>0.09</td>
</tr>
<tr>
<td>P_{C1d}</td>
<td>0.10</td>
</tr>
<tr>
<td>P_{C2d}</td>
<td>0.06</td>
</tr>
<tr>
<td>P_{C3d}</td>
<td>0.06</td>
</tr>
<tr>
<td>P_{C1e}</td>
<td>0.05</td>
</tr>
<tr>
<td>P_{C2e}</td>
<td>0.06</td>
</tr>
<tr>
<td>P_{C3e}</td>
<td>0.08</td>
</tr>
<tr>
<td>P_{C1f}</td>
<td>0.05</td>
</tr>
<tr>
<td>P_{C2f}</td>
<td>0.05</td>
</tr>
<tr>
<td>P_{C3f}</td>
<td>0.10</td>
</tr>
<tr>
<td>P_{C3g}</td>
<td>0.05</td>
</tr>
<tr>
<td>P_{C3h}</td>
<td>0.30</td>
</tr>
</tbody>
</table>

### TABLE V
PROBABILITIES CALCULATED BY EQUATIONS

<table>
<thead>
<tr>
<th>Event</th>
<th>Probability</th>
</tr>
</thead>
<tbody>
<tr>
<td>P_{C1}</td>
<td>0.84 * 10^{-6}</td>
</tr>
<tr>
<td>P_{C2}</td>
<td>6.0 * 10^{-6}</td>
</tr>
<tr>
<td>P_{C3}</td>
<td>0.0091 * 10^{-6}</td>
</tr>
<tr>
<td>P_C</td>
<td>6.85 * 10^{-6}</td>
</tr>
</tbody>
</table>

### VI. CONCLUSION

In this paper, we presented the behavioral and probabilistic model of Software risk Identification by using the probabilistic calculations of Fault Tree Analysis, and the following conclusions are drawn:
- Focuses on software risk identification, mainly the SEI-Software Development Risk Taxonomy, because it is more detailed than many other approaches. This Taxonomy is useful for software development organizations as it is very efficient.
- Applying Fault Tree Analysis approach on SEI Software Development Risk Taxonomy, by using Boolean OR/AND gates and assigning probabilities of these risks, we were able to compute an expression for the overall probability of the whole system.
- FTA is a proven method for identifying and evaluating risk in high hazard applications that has the potential failure.
- Identify all the causes that can make the top event occur using fault tree symbols and the logic tree format. More specifically, by using deductive reasoning highlight event that can lead to the occurrence of the top event.
- The advantage of this approach is the dynamic monitoring and estimation of various probabilities of risks, because it was appropriate by combining the hierarchical model of the risks (TSDS) and Fault Tree Analysis. Furthermore it can help software risk management process. This probabilistic risk tree structure can apply to some software tools.
APPENDIX A: FAULT TREE ANALYSIS FOR SOFTWARE DEVELOPMENT RISK

A. Development Cycle Risks

B. Development Environment Risks

C. Programmatic Risks

1. Requirement Risks
2. Design Risks
3. Implementation Risks
4. Test and Evaluation Risks
   a. Predictability
   b. Suitability
   c. Completeness
   d. Clarity
   e. Accuracy
   f. Functionality
   g. Integration
   h. Execution Performance Expectations
   i. Support

1. Development Process Risks
2. Management Risks
   a. Quality Assurance
   b. Planning
   c. Process Control
   d. Quality Management
   e. Configuration Management
   f. Risk Management
   g. Performance Management
2. Project Risks
   a. Project Management
   b. Human Resource Management
   c. Financial Management
   d. Technical Management
   e. Time Management
   f. Management Style
   a. Customer Commitment
   b. User Commitment
   c. Sponsor Alignment
   d. Subcontractor Alignment
   e. Prime Contractor
   f. Corporate Communication
   g. Vendor Performance
   h. Political

1. Environment Risks
2. Contract Risks
3. Program Interface Risks
4. Management Methods Risks
5. Work Environment Risks

a. Schedule
b. Staff
i. Unit Testing
ii. Integration Testing
iii. Interoperability Testing

1. Development Process Risks
2. Management Risks
   a. Quality Assurance
   b. Planning
   c. Process Control
   d. Quality Management
   e. Configuration Management
   f. Risk Management
   g. Performance Management
2. Project Risks
   a. Project Management
   b. Human Resource Management
   c. Financial Management
   d. Technical Management
   e. Time Management
   f. Management Style
   a. Customer Commitment
   b. User Commitment
   c. Sponsor Alignment
   d. Subcontractor Alignment
   e. Prime Contractor
   f. Corporate Communication
   g. Vendor Performance
   h. Political
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